

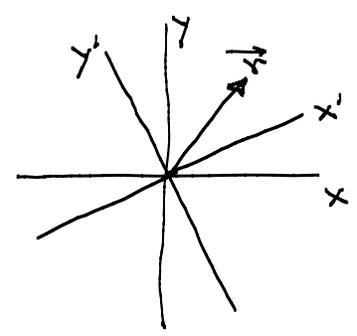
Phys 366

Lectures 7-8

Vector fields, gradient, and divergence

Fields

Scalar fields: pressure $p(\vec{r})$
 temperature $T(\vec{r})$
 number density $n(\vec{r})$
 mass density $\rho(\vec{r})$
 probability density $\psi(\vec{r})$



$$\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$= x'\hat{x}' + y'\hat{y}' + z'\hat{z}'$$

$$p(x, y, z) = p(x', y', z')$$

pseudoscalar?

Vector fields: force field $\vec{F}(\vec{r}) = m\vec{g}(\vec{r})$
 ↑ ↑
 gravitational force gravitational field

$$\vec{F}(\vec{r}) = q\vec{E}(\vec{r}) + \nabla \times \vec{B}(\vec{r})$$

↑ ↑ ↑
 Lorentz force electric field magnetic field

fluid velocity $\vec{v}(\vec{r})$

$$v_j(x, y, z) = \hat{e}_j \cdot \vec{v}(\vec{r})$$

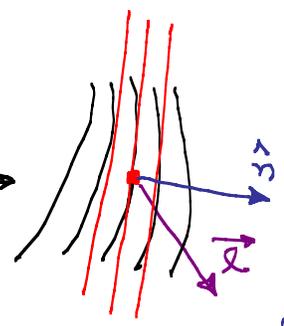
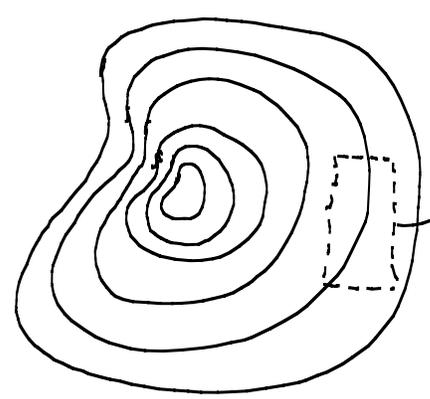
$$= \sum_x \hat{e}_j \cdot \hat{e}'_k \hat{e}'_k \cdot \vec{v}(\vec{r})$$

$$= \sum_k \hat{e}_j \cdot \hat{e}'_k v'_k(x', y', z')$$

pseudovector?

Gradient: local (linear) approximation to level structure (contours) of a scalar function f .

Scalar field $f(\vec{r})$



$$\Delta s = \Delta l \hat{s} \cdot \hat{x}$$

$$\text{grad } f = \nabla f = \hat{s} \frac{\Delta f}{\Delta s} = \hat{s} \frac{df}{ds}$$

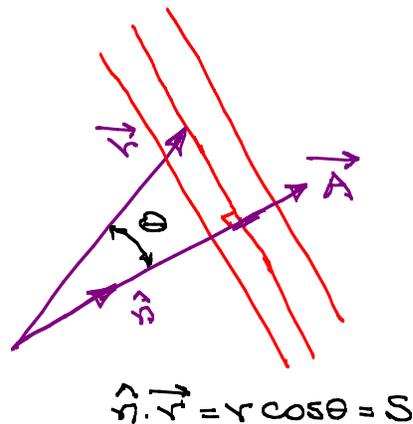
derivative of f along direction of steepest ascent

Examples:

① Linear function

$$f(\vec{r}) = \vec{A} \cdot \vec{r} = A \hat{n} \cdot \vec{r}$$

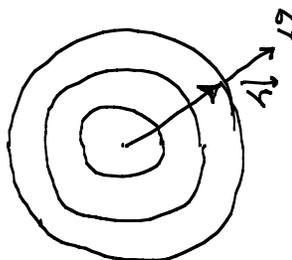
$$\nabla f = \frac{df}{ds} \hat{s} = A \hat{n} = \vec{A}$$



② Spherically symmetric function

$$f(\vec{r}) = f(r)$$

$$\nabla f = \frac{df}{dr} \hat{r}$$



$$\frac{df}{ds} = \frac{df}{dr}$$

Directional derivative

$$\frac{\partial f}{\partial l} = \frac{\Delta f}{\Delta l} = \hat{l} \cdot \nabla f = \hat{l} \cdot \nabla f$$

Cartesian components

$$\frac{\partial f}{\partial x} = \hat{x} \cdot \nabla f, \quad \frac{\partial f}{\partial y} = \hat{y} \cdot \nabla f, \quad \frac{\partial f}{\partial z} = \hat{z} \cdot \nabla f, \quad \frac{\partial f}{\partial x_j} = \nabla f \cdot \hat{e}_j$$

$$\nabla f = \sum_j \hat{e}_j (\hat{e}_j \cdot \nabla f) = \sum_j \frac{\partial f}{\partial x_j} \hat{e}_j$$

$$\nabla \text{ as an operator: } \nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} = \sum_j \hat{e}_j \frac{\partial}{\partial x_j}$$

Curvilinear coordinates:

① Cylindrical: $\frac{\partial f}{\partial \rho} = \hat{\rho} \cdot \nabla f, \quad \frac{1}{\rho} \frac{\partial f}{\partial \phi} = \hat{\phi} \cdot \nabla f, \quad \frac{\partial f}{\partial z} = \hat{z} \cdot \nabla f$

$\hat{e} = \hat{\rho}$

$$\nabla f = \hat{\rho} \frac{\partial f}{\partial \rho} + \hat{\phi} \frac{1}{\rho} \frac{\partial f}{\partial \phi} + \hat{z} \frac{\partial f}{\partial z}$$

② Spherical: $\frac{\partial f}{\partial r} = \hat{r} \cdot \nabla f$, $\frac{1}{r} \frac{\partial f}{\partial \theta} = \hat{\theta} \cdot \nabla f$, $\frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} = \hat{\phi} \cdot \nabla f$

$$\nabla f = \hat{r} \frac{\partial f}{\partial r} + \hat{\theta} \frac{1}{r} \frac{\partial f}{\partial \theta} + \hat{\phi} \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi}$$

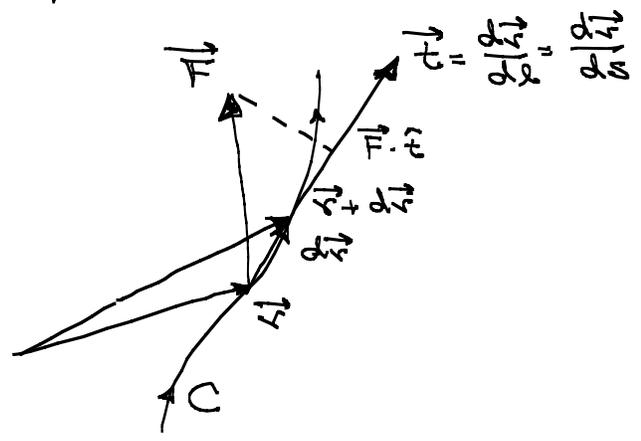
Integral representation

Line integrals

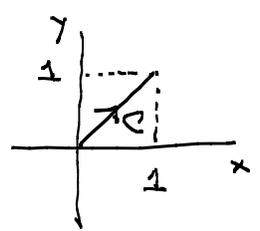
$$\int_C \vec{F} \cdot d\vec{r} = \int_{x_i}^{x_f} \vec{F} \cdot \frac{d\vec{r}}{dr} dr$$

\uparrow
 $d\vec{r}$ or $d\vec{s}$

could be work transporting a particle along C

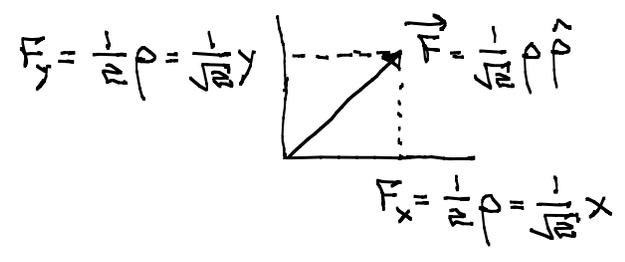


Example: $\vec{F}(\vec{r}) = \hat{\rho} \rho \cos \phi = x \hat{\rho}$



$$\int_C \vec{F} \cdot d\vec{r} = \int_0^{\sqrt{2}} dp \rho \cos \phi = \frac{1}{\sqrt{2}} \int_0^{\sqrt{2}} dp \rho = \frac{1}{\sqrt{2}} \left[\frac{\rho^2}{2} \right]_0^{\sqrt{2}} = \frac{1}{\sqrt{2}}$$

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_0^1 dx x \hat{x} + \int_0^1 dy y \hat{y} \\ &= \frac{1}{\sqrt{2}} \int_0^1 x dx + \frac{1}{\sqrt{2}} \int_0^1 y dy \\ &= \frac{1}{\sqrt{2}} \end{aligned}$$



Path dependence? Closed curves? Stokes theorem?

Work-energy theorem:

$$\begin{aligned}
 \left(\text{work done by force } \vec{F} \text{ along curve } C \right) &= \int_C \vec{F} \cdot d\vec{r} \\
 &= \int_C \vec{F} \cdot \frac{d\vec{r}}{dt} dt && \text{we are not using arc length to parameterize the curve} \\
 &= \int_C \vec{F} \cdot \vec{v} dt \\
 &= \int_C m \vec{a} \cdot \vec{v} dt \\
 &= \int_C \frac{d}{dt} \left(\frac{1}{2} m \vec{v} \cdot \vec{v} \right) dt \\
 & && T = (\text{kinetic energy}) \\
 &= \int_C dT \\
 &= \Delta T
 \end{aligned}$$

If the force is conservative,

$$\vec{F} = -\nabla V$$

↑
potential energy

Newton's gravity

$$\vec{F} = m\vec{g} = -m\nabla\Phi$$

↑
gravitational potential

Electrostatics

$$\vec{F} = q\vec{E} = -q\nabla\phi$$

↑
electrostatic potential

Magnetic force \vec{F}_B

$$\begin{aligned}
 \int_C \vec{F} \cdot d\vec{r} &= -\int_C \nabla V \cdot d\vec{l} \\
 &= -\int_{x_i}^{x_f} \frac{\partial V}{\partial l} dl \\
 &= -(V_f - V_i) \\
 &= -\Delta V
 \end{aligned}$$

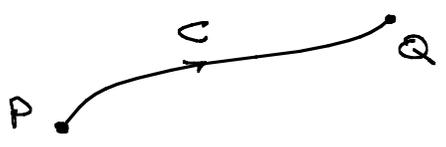
$$\implies \Delta(T + V) = 0$$

Conservation of mechanical energy

Fundamental theorem of calculus:

$$\int_C \nabla f \cdot d\vec{l} = f(Q) - f(P)$$

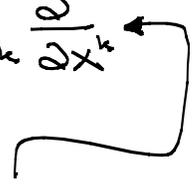
$$\oint_C \nabla f \cdot d\vec{l} = 0$$



Is ∇f a vector? Passive transformation of position vector

$$X'_j = \hat{e}'_j \cdot \vec{r} = \underbrace{\hat{e}'_j \cdot \hat{e}_k}_{M_{jk}} X_k, \quad \hat{e}'_j = \hat{e}_k \underbrace{(\hat{e}_k \cdot \hat{e}'_j)}_{M_{jk}}$$

$$X_k = \hat{e}_k \cdot \vec{r} = \underbrace{\hat{e}_k \cdot \hat{e}'_j}_{M_{jk}} X'_j, \quad \hat{e}_k = \hat{e}'_j \underbrace{(\hat{e}'_j \cdot \hat{e}_k)}_{M_{jk}}$$

$$\frac{\partial \varphi}{\partial X'_j} = \frac{\partial \varphi}{\partial X_k} \frac{\partial X_k}{\partial X'_j} = M_{jk} \frac{\partial \varphi}{\partial X^k}$$


These derivatives transform like vectors, so ∇f is a vector. Move to the point, ∇ transforms like a vector operator.

Divergence

Vector field $\vec{F}(\vec{r})$ or $\text{div } \vec{F}$

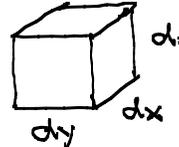
We need to do a little work on volume and surface integrals first.

Volume integrals

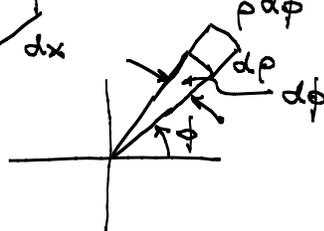
$\int_V f(\vec{r}) dV$

$\frac{d^3}{dx dy dz}$ ← textbook

$f(x, y, z) dx dy dz$



$f(\rho, \phi, z) \frac{d\rho}{\rho} d\phi dz$

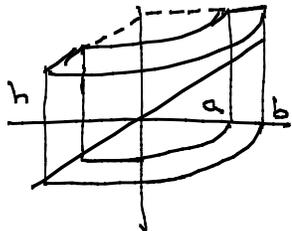


$\frac{d\rho}{\rho} d\phi dz$

$f(r, \theta, \phi) dr r d\theta r \sin\theta d\phi$

$r^2 \sin\theta dr d\theta d\phi = r^2 dr \underbrace{\sin\theta d\theta d\phi}_{d\Omega}$

solid angle (steradians)



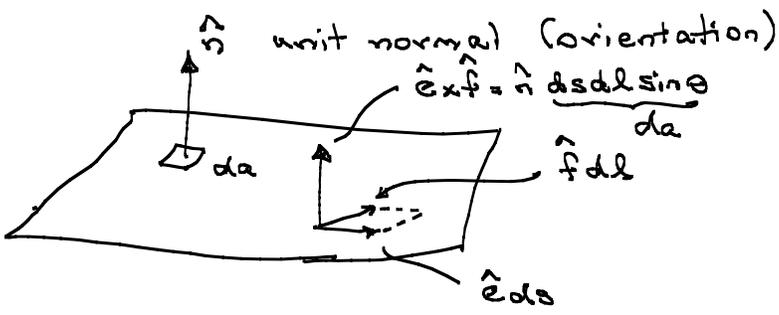
$$\int_a^b \rho d\rho \int_0^{\pi/2} d\phi \int_0^h dz f(\rho, \phi, z)$$

Surface integrals

$\int_S \vec{F} \cdot d\vec{a}$

$\hat{n} da = \hat{n} d\sigma$

↑
 textbook



Cartesian and curvilinear
 Closed surfaces (orientation)

A volume is bounded by a closed surface (orientation?)

The closed surface has no boundary

An open surface is bounded by a closed curve (orientation?)

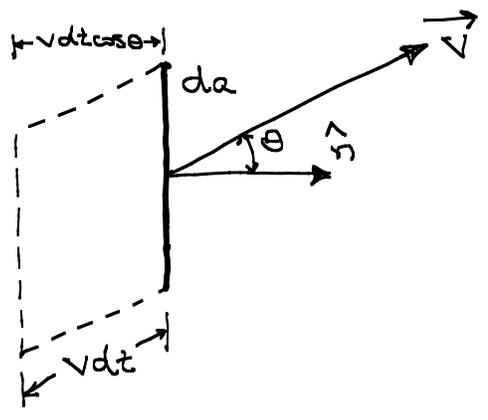
The closed curve has no boundary.

An open curve is bounded by two points. The points have no boundary.

unique?

(Flux of \vec{F} through S) = $\int_S \vec{F} \cdot d\vec{a}$. This comes from transport theory:

Particles with number density $n(\vec{r})$ and velocity $\vec{v}(\vec{r})$.



(number of particles that pass through da in time dt) = $n da v dt \cos \theta = n \vec{v} \cdot d\vec{a} dt$

(flux of particles through da) = $n \vec{v} \cdot d\vec{a}$

Many sorts of particles: n_α, \vec{v}_α

(flux of particles through da) = $\sum_\alpha n_\alpha \vec{v}_\alpha \cdot d\vec{a}$

$n \langle \vec{v} \rangle$

$n = \sum_\alpha n_\alpha$
 $\langle \vec{v} \rangle = \frac{1}{n} \sum_\alpha n_\alpha \vec{v}_\alpha$

(flux of particles through S) = $\int_S n \langle \vec{v} \rangle \cdot d\vec{a}$

Particles carrying some property, e.g., charge: q, n, \vec{v}

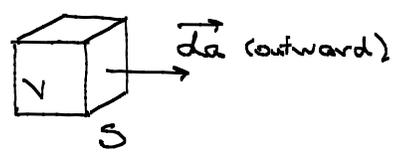
(flux of charge through $d\vec{a}$) = $\sum_{\alpha} q n_{\alpha} \vec{v}_{\alpha} \cdot d\vec{a}$

"
(current through $d\vec{a}$) $\equiv \vec{J} =$ (current density) = $q n \langle \vec{v} \rangle$

(charge density) = $\rho = q n = q \sum_{\alpha} n_{\alpha}$

(current through S) = $\int_S \vec{J} \cdot d\vec{a}$

Divergence of a vector field



Shape of volume?

$\text{div } \vec{F} dV = \nabla \cdot \vec{F} dV \equiv \int_S \vec{F} \cdot d\vec{a}$

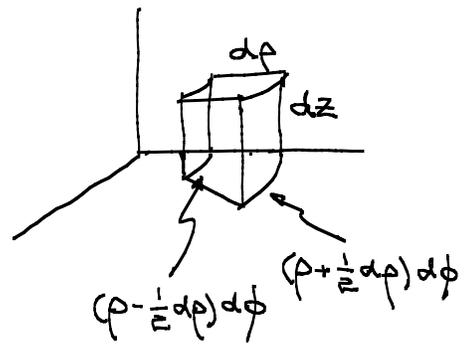
$\nabla \cdot \vec{F}$ is the differential version of outward flux.

Components

Cartesian: $\int_S \vec{F} \cdot d\vec{a} = \sum_j \underbrace{F_j (x_j + \frac{1}{2} dx_j) da_j - F_j (x_j - \frac{1}{2} dx_j) da_j}_{\frac{\partial F_j}{\partial x_j} dx_j da_j} = dV \sum_j \frac{\partial F_j}{\partial x_j}$

$\nabla \cdot \vec{F} = \sum_j \frac{\partial F_j}{\partial x_j} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$ ∇ operator

Cylindrical: $\int_S \vec{F} \cdot d\vec{a} = \underbrace{F_p(\rho + \frac{1}{2} d\rho)(\rho + \frac{1}{2} d\rho) d\phi dz - F_p(\rho - \frac{1}{2} d\rho)(\rho - \frac{1}{2} d\rho) d\phi dz}_{\frac{\partial(\rho F_p)}{\partial \rho} d\rho d\phi dz = \frac{1}{\rho} \frac{\partial(\rho F_p)}{\partial \rho} dV}$



$+ F_{\phi}(\phi + \frac{1}{2} d\phi) d\rho dz - F_{\phi}(\phi - \frac{1}{2} d\phi) d\rho dz$

$\frac{\partial F_{\phi}}{\partial \phi} d\rho d\phi dz = \frac{1}{\rho} \frac{\partial F_{\phi}}{\partial \phi} dV$

$+ F_z(z + \frac{1}{2} dz) d\rho d\phi - F_z(z - \frac{1}{2} dz) d\rho d\phi$

$\frac{\partial F_z}{\partial z} \rho d\rho d\phi dz = \frac{\partial F_z}{\partial z} dV$

$$\nabla \cdot \vec{F} = \frac{1}{\rho} \frac{\partial(\rho F_\rho)}{\partial \rho} + \frac{1}{\rho} \frac{\partial F_\phi}{\partial \phi} + \frac{1}{\rho} \frac{\partial(\rho F_z)}{\partial z}$$

area \perp to differentiation $\rho d\phi dz$ $d\rho dz$ $d\rho \rho d\phi$
 length along differentiation $d\rho$ $\rho d\phi$ dz

$$\nabla \cdot \vec{F} = \frac{1}{\rho} \frac{\partial(\rho F_\rho)}{\partial \rho} + \frac{1}{\rho} \frac{\partial F_\phi}{\partial \phi} + \frac{\partial F_z}{\partial z}$$

General orthogonal curvilinear coordinates: The derivation for cylindrical coordinates is enough to teach us how to get the divergence for any orthogonal coordinates. Suppose we have orthogonal coordinates x_1, x_2, x_3 , with orthonormal basis vectors $\hat{x}_1, \hat{x}_2, \hat{x}_3$. Length along x_j is given by $h_j dx_j$, i.e., $h_1 dx_1, h_2 dx_2$, and $h_3 dx_3$, so the volume element is $dV = h_1 h_2 h_3 dx_1 dx_2 dx_3$. The two effects, for the derivative with respect to one of the coordinates, are (i) the change in the area element from the front to the back of dV due to the other two coordinates and (ii) the conversion of the derivative to length. So we get

$$\nabla \cdot \vec{F} = \frac{1}{h_1 h_2 h_3} \frac{\partial(h_2 h_3 F_1)}{\partial x_1} + \frac{1}{h_2 h_3 h_1} \frac{\partial(h_1 h_3 F_2)}{\partial x_2} + \frac{1}{h_3 h_1 h_2} \frac{\partial(h_1 h_2 F_3)}{\partial x_3}$$

area \perp to differentiation $h_2 h_3 dx_2 dx_3$ $h_1 h_3 dx_1 dx_3$ $h_1 h_2 dx_1 dx_2$
 length along differentiation $h_1 dx_1$ $h_2 dx_2$ $h_3 dx_3$

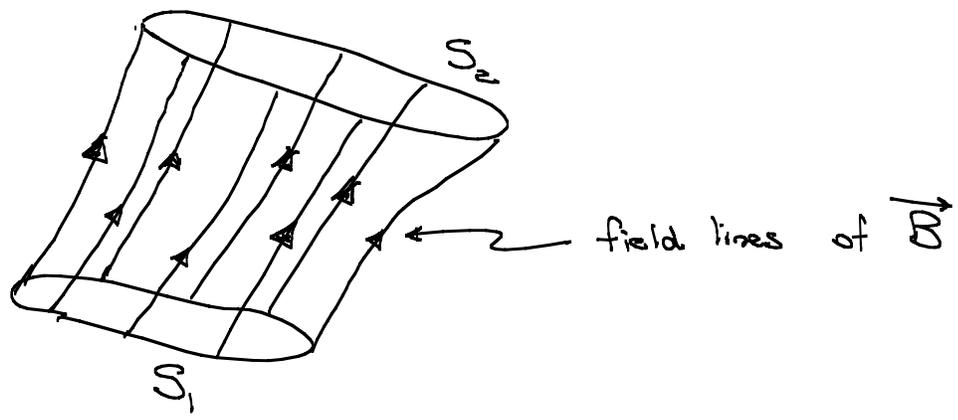
OR
$$\nabla \cdot \vec{F} = \sum_j \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial x_j} \left(\frac{h_1 h_2 h_3}{h_j} F_j \right)$$

Spherical:
$$\nabla \cdot \vec{F} = \frac{1}{r^2} \frac{\partial(r^2 F_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\sin \theta F_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi}$$

area \perp to differentiation $r d\theta r \sin \theta d\phi$ $dr r \sin \theta d\phi$ $dr r d\theta$
 length along differentiation dr $r d\theta$ $r \sin \theta d\phi$

Field lines and conservation of flux

$$\nabla \cdot \vec{B} = 0$$



$$0 = \int_V \nabla \cdot \vec{B} dV = \int_{S_2} \vec{B} \cdot d\vec{a}_2 - \int_{S_1} \vec{B} \cdot d\vec{a}_1 + \int_{\text{sides}} \vec{B} \cdot d\vec{a}$$

↑ upward ↑ upward ○ since \vec{B} is tangent to the sides

Flux of a divergenceless field is conserved:

$$\int_{S_2} \vec{B} \cdot d\vec{a} = \int_{S_1} \vec{B} \cdot d\vec{a}$$

This is what we have in mind when we draw field lines: as the field lines get closer together (further apart), the field gets stronger (weaker).

Is $\nabla \cdot \vec{F}$ a scalar?

$$\frac{\partial F'_j}{\partial x'_j} = M_{jk} \frac{\partial}{\partial x^k} (M_{je} F_e) = \underbrace{(M^{-1})_{kj} M_{je}}_{\delta_{ke}} \frac{\partial F_e}{\partial x^k} = \frac{\partial F'_k}{\partial x^k}$$

What this does is to use the transformation of ∇ as a vector operator to show $\nabla \cdot \vec{F}$ is a scalar.

Laplacian: $\nabla^2 f = \nabla \cdot \nabla f$

$\nabla^2 f$ is a
scalar field

Cartesian coordinates: $\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$

General orthogonal curvilinear coordinates:

Lengths $h_1 dx_1$ $h_2 dx_2$ $h_3 dx_3$

$$\nabla f = \sum_j \frac{1}{h_j} \frac{\partial f}{\partial x_j}$$

$$\nabla \cdot \vec{F} = \sum_j \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial x_j} \left(\frac{h_1 h_2 h_3}{h_j} F_j \right)$$

$$\nabla^2 f = \nabla \cdot \nabla f = \sum_j \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial x_j} \left(\frac{h_1 h_2 h_3}{h_j} \frac{\partial f}{\partial x_j} \right)$$