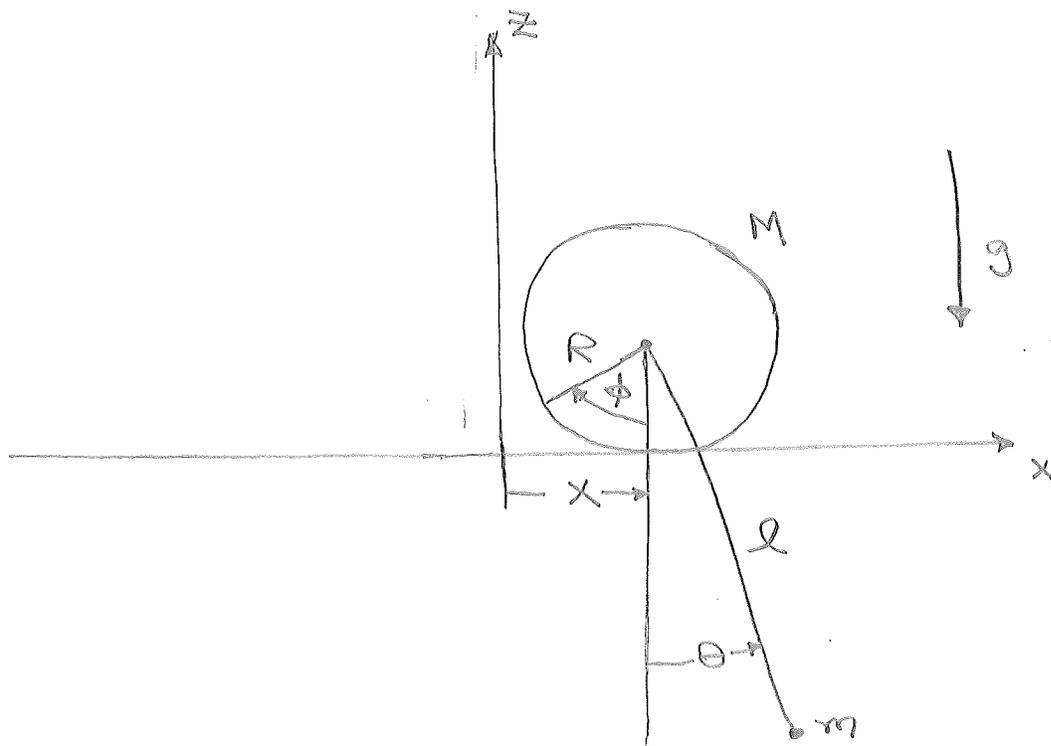


Phys 503  
Midterm Exam #1  
Solutions

1.



(a) Generalized coordinates:  $X, \theta$

$X$  is the displacement of the CM of cylinder. The rolling constraint implies that  $X = R\phi$ , where  $\phi$  is the angle through which the cylinder has rolled.

$\theta$  is angle of the pendulum relative to vertical. The Cartesian (inertial) coordinates of  $m$  are

$$\begin{aligned} x &= X + l \sin \theta & \dot{x} &= \dot{X} + l \dot{\theta} \cos \theta \\ z &= R - l \cos \theta & \dot{z} &= -l \dot{\theta} \sin \theta \end{aligned} \Rightarrow$$

(b) Lagrangian:

$$T = T_{M, \text{trans}} + T_{M, \text{rot}} + T_m$$

$$T_{M, \text{trans}} = \frac{1}{2} M \dot{X}^2$$

$$T_{M, \text{rot}} = \frac{1}{2} M R^2 \dot{\phi}^2 = \frac{1}{2} M \dot{X}^2$$

$$T_m = \frac{1}{2} m (\dot{X}^2 + \dot{z}^2)$$

$$= \frac{1}{2} m (\dot{X}^2 + 2l \dot{X} \dot{\theta} \cos \theta + l^2 \dot{\theta}^2 \cos^2 \theta + l^2 \dot{\theta}^2 \sin^2 \theta)$$

$$= \frac{1}{2} m (\dot{X}^2 + 2l \dot{X} \dot{\theta} \cos \theta + l^2 \dot{\theta}^2)$$

$$T = \frac{1}{2} (2M + m) \dot{X}^2 + ml \dot{X} \dot{\theta} \cos \theta + \frac{1}{2} ml^2 \dot{\theta}^2$$

$$V = mgz + (\text{const}) = -mgl \cos \theta$$

$$L = T - V$$

$$= \frac{1}{2} (2M + m) \dot{X}^2 + ml \dot{X} \dot{\theta} \cos \theta + \frac{1}{2} ml^2 \dot{\theta}^2 + mgl \cos \theta$$

(c) Conserved quantities:

①  $X$  is cyclic  $\Rightarrow P_X = \frac{\partial L}{\partial \dot{X}}$  is conserved

$$P_X = \frac{\partial L}{\partial \dot{X}} = (2M+m)\dot{X} + ml\dot{\theta}\cos\theta$$

$$= M\dot{X} + \underbrace{M\dot{X} + ml\dot{\theta}\cos\theta}_{\text{x-component of linear momentum}}$$

x-component of  
linear momentum

②  $E = h =$  Jacobi integral

$$E = T + V = \frac{1}{2}(2M+m)\dot{X}^2 + ml\dot{X}\dot{\theta}\cos\theta + \frac{1}{2}ml^2\dot{\theta}^2 - mgl\cos\theta$$

2. Arbitrary Kepler orbit:  $\frac{1}{r} = \frac{mk}{l^2} (1 + e \cos \theta)$

$$e = \sqrt{1 + \frac{2l^2 E}{mk^2}}$$

(a) Initial orbit is parabolic:  $E=0 \Leftrightarrow e=1$

$$\frac{1}{r} = \frac{mk}{l^2} (1 + \cos \theta)$$

Impulse at periastron ( $\theta=0$ ), where  $r = \frac{l^2}{2mk}$

Final circular orbit:  $e=0$

$$r = \frac{l'^2}{mk} = \frac{l^2}{2mk} \Rightarrow$$

$$l' = l/\sqrt{2}$$

$$E' = -\frac{mk^2}{2l'^2}$$

$$E' = -\frac{mk^2}{l^2}$$

$$(E' = -\frac{k}{2r} = -\frac{mk^2}{2l'^2})$$

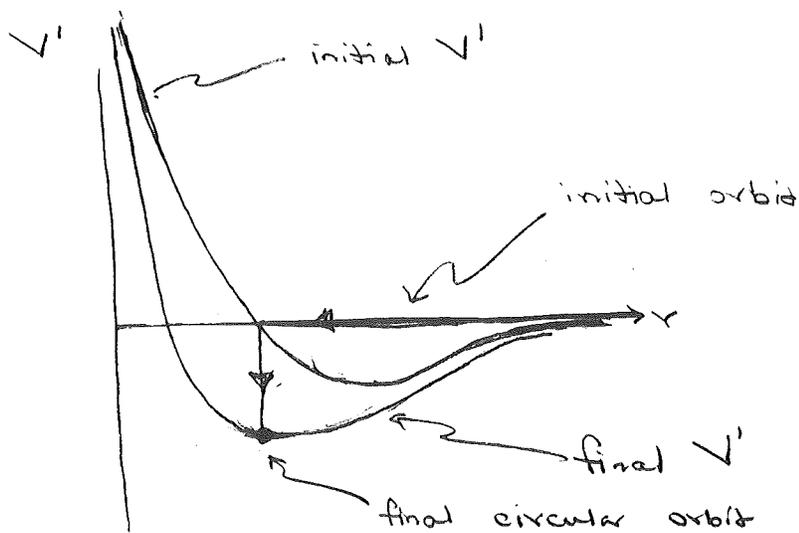
Impulse: Since  $\dot{r}=0$  at periastron, there is no radial impulse.

The required impulse is purely angular, and it is in the  $-\theta$  direction to remove the excess angular momentum.

$$S_{\theta} = \int F_{\theta} dt = \Delta P_{\theta} = m r \Delta \dot{\theta} = \frac{\Delta l}{r}$$

$$\therefore S_{\theta} = \frac{2mk}{l^2} (l' - l) = \frac{2mk}{l} \underbrace{\frac{l' - l}{l}}_{\left(\frac{1}{\sqrt{2}} - 1\right)} = \frac{mk}{l} (\sqrt{2} - 2) = S_{\theta}$$

negative as required



(b) Initial orbit is arbitrary elliptical:

$$\frac{1}{r} = \frac{mk}{l^2} (1 + e \cos \theta), \quad e < 1$$

Impulse at  $\theta = \pi/2$ , where  $r = \frac{l^2}{mk}$

Final circular orbit:  $e = 0$

$$r = \frac{l'^2}{mk} = \frac{l^2}{mk} \Rightarrow$$

$$l' = l, \quad \Delta l = 0$$

$$E' = -\frac{mk^2}{2l'^2} = -\frac{mk^2}{2l^2} = E'$$

Impulse: Since  $\Delta l = 0$ , there is no angular impulse.

The impulse is purely radial, and it is in the  $-r$  direction to remove the radial kinetic energy.

$$S_r = \int F_r dt = \Delta P_r$$

Initial orbit:  $E = \frac{P_r^2}{2m} - \frac{k}{r} + \frac{l^2}{2mr^2}$

Final orbit:  $E' = -\frac{k}{r} + \frac{l^2}{2mr^2}$

$$\Rightarrow \Delta E = E' - E = -\frac{P_r^2}{2m} = -\frac{(\Delta P_r)^2}{2m} = -\frac{S_r^2}{2m}$$

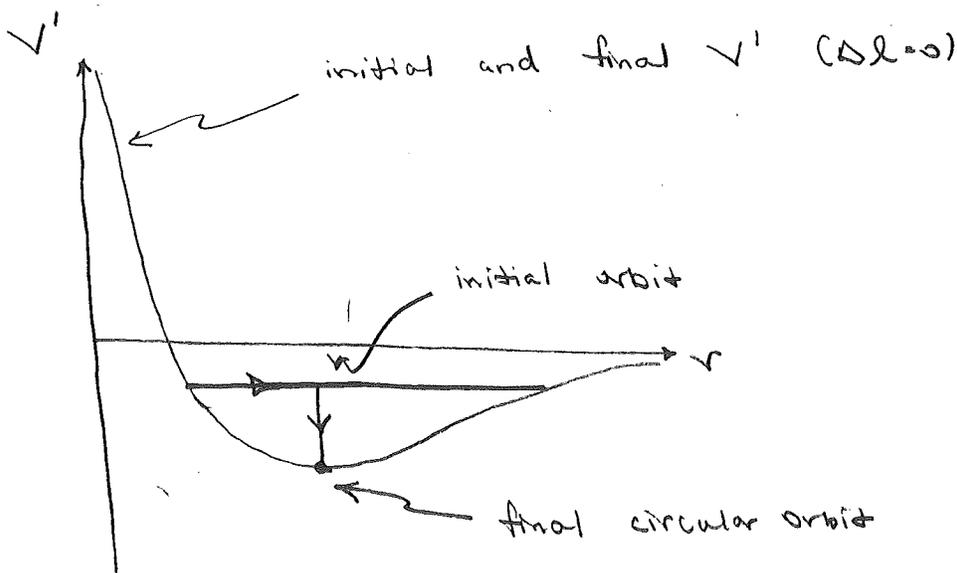
$$S_r^2 = -2m \Delta E \Rightarrow S_r = \sqrt{2m(E - E')}$$

negative impulse

$$2mE + \frac{m^2 k^2}{l^2}$$

$$S_r = -\frac{mk}{l} \sqrt{1 + \frac{2l^2 E}{mk^2}} = -\frac{mk}{l} e$$

This actually works for all  $e$ , not just  $e < 1$ .



$$E' = -\frac{mk^2}{2l^2} \Rightarrow E - E' = \frac{mk^2}{2l^2} e^2 \Rightarrow S_r = -\frac{mk}{l} e$$

$$E = -\frac{mk^2}{2l^2} (1 - e^2)$$

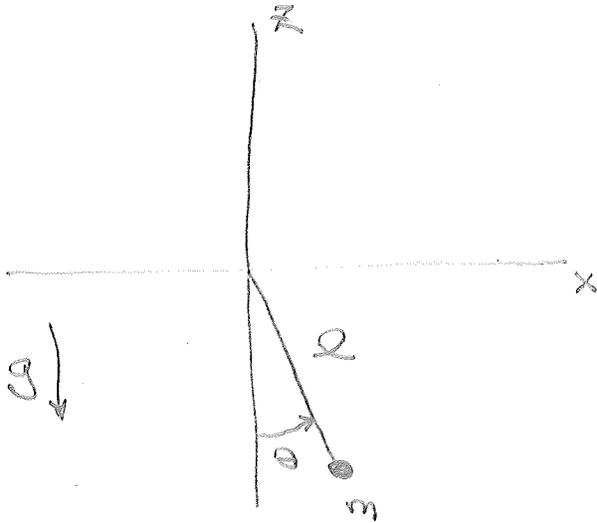
Alternative method to get  $\Delta P_r$ :

$$\begin{aligned} S_r = \Delta P_r = m_i \Delta v &= -P_r = -\sqrt{2m} \left[ E + \frac{k}{r} - \frac{\lambda^2}{2m\hbar^2} \right]^{1/2} \\ &= E + \frac{mk^2}{e^2} - \frac{\lambda^2 m^2 k^2}{2\hbar^2 e^4} \\ &= E + \frac{mk^2}{2e^2} \\ &= \frac{mk^2}{2e^2} \left( 1 + \frac{2\lambda^2 E}{mk^2} \right) \end{aligned}$$

$$S_r = -\frac{mk}{e} \sqrt{1 + \frac{2\lambda^2 E}{mk^2}} = -\frac{mk}{e} e$$

# Problem 3

①



$$x = r \sin \theta$$

$$z = -r \cos \theta$$

$$V = mgz = -mgr \cos \theta$$

$$T = \frac{1}{2} m (\dot{x}^2 + \dot{z}^2) = \frac{1}{2} m (r^2 \dot{\theta}^2 + r^2 \dot{\theta}^2)$$

(a)  $L' = T - V - \lambda(r-l)$

$$= \frac{1}{2} m r^2 \dot{\theta}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 + mgr \cos \theta - \lambda(r-l)$$

$$\frac{\partial L'}{\partial r} = m \dot{\theta}^2, \quad \frac{d}{dt} \left( \frac{\partial L'}{\partial \dot{r}} \right) = m \ddot{r}$$

$$\rightarrow m \ddot{r} = m r \dot{\theta}^2 + mgr \cos \theta - \lambda$$

$$\frac{\partial L'}{\partial r} = m r \dot{\theta}^2 + mgr \cos \theta - \lambda$$

$$\frac{\partial L'}{\partial \dot{\theta}} = m r^2 \dot{\theta}, \quad \frac{d}{dt} \left( \frac{\partial L'}{\partial \dot{\theta}} \right) = m r^2 \ddot{\theta} + 2 m r \dot{r} \dot{\theta}$$

$$\frac{\partial L'}{\partial \theta} = -mgr \sin \theta \quad \rightarrow \quad m r^2 \ddot{\theta} + 2 m r \dot{r} \dot{\theta} = -mgr \sin \theta$$

Apply constraint:  $r=l$

$\rightarrow$  centrifugal force  $\rightarrow$   $\lambda = T = \text{tension}$   
 $0 = m l \dot{\theta}^2 + \underbrace{mgr \cos \theta}_{\rightarrow \text{gravity}} - \lambda$   $T$  is positive inward

$m l \ddot{\theta} = -mgr \sin \theta$

(b) The impulse gives the mass a momentum  $S$  and a kinetic energy  $S^2/2m$ . The conserved energy is

$$E = T + V = \underbrace{\frac{S^2}{2m}}_{\text{initial value}} - mgl = \underbrace{\frac{1}{2}ml\dot{\theta}^2 + mgl\cos\theta}_{\text{value at any time}}$$

If the string were a rigid rod, it would get to a maximal angle  $\theta_m$  ( $\dot{\theta}=0$ ) given by

$$mgl\cos\theta_m = mgl - \frac{S^2}{2m}$$

$$\boxed{\cos\theta_m = 1 - \frac{S^2}{2m^2gl}}$$

The tension  $J = \lambda$  is given by

$$J = ml\dot{\theta}^2 + mg\cos\theta$$

$$\frac{1}{2}lJ = \frac{1}{2}ml\dot{\theta}^2 + \frac{1}{2}mgl\cos\theta$$

$$\left\{ \begin{array}{l} \frac{S^2}{2m} + mgl(\cos\theta - 1) \end{array} \right.$$

$$= \frac{S^2}{2m} - mgl + \frac{3}{2}mgl\cos\theta$$

Writing this in dimensionless form, we have

$$\frac{J}{2mg} = \frac{S^2}{2m^2gl} - 1 + \frac{3}{2}\cos\theta$$

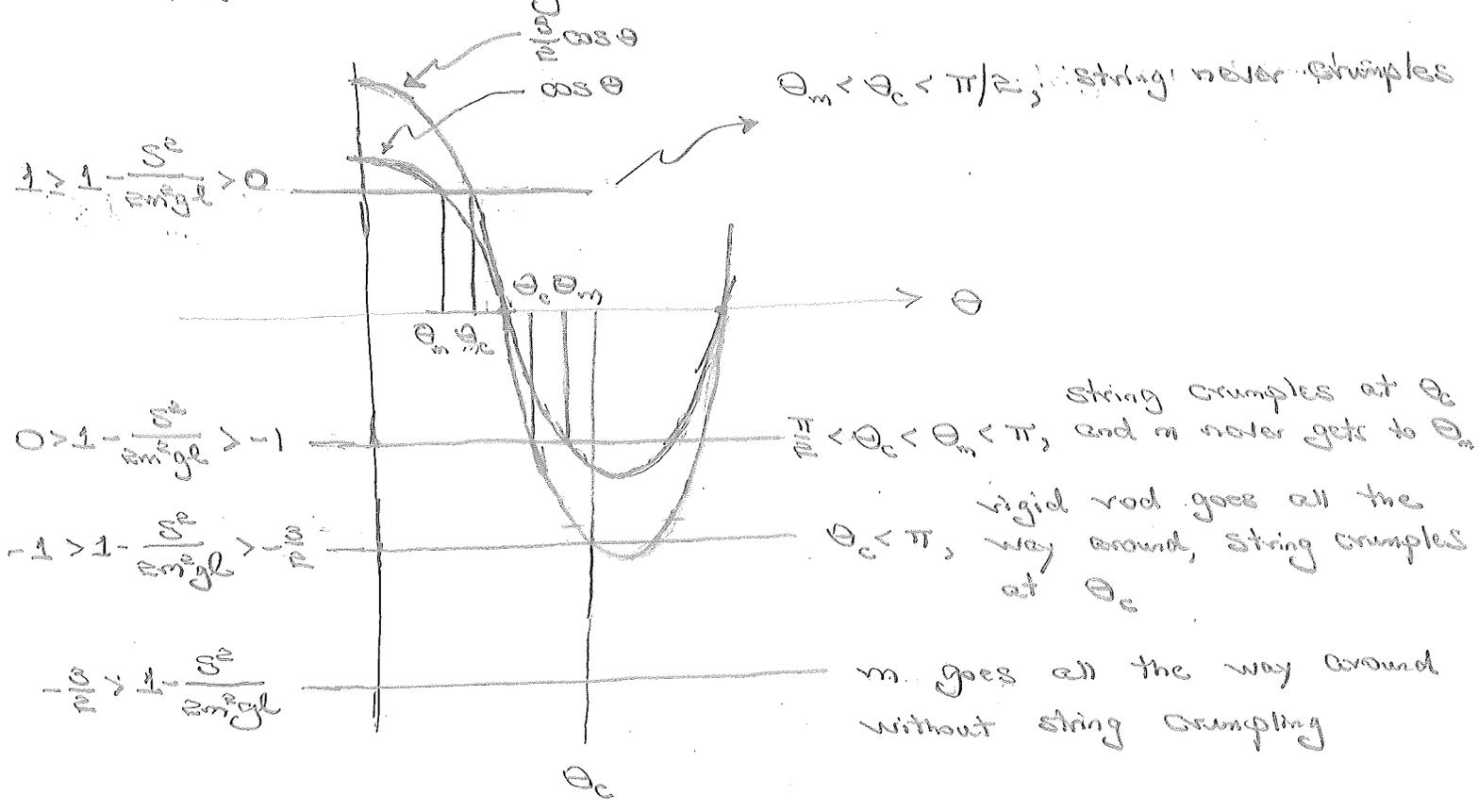
The string can only pull inward ( $J > 0$ ), not push outward ( $J < 0$ ), so the string crumples

when  $J=0$ , i.e., at angle  $\theta_c$  given by

$$0 = \frac{g^2}{2m^2gl} - 1 + \frac{p/a}{m} \cos \theta_c$$

$$\rightarrow \frac{p/a}{m} \cos \theta_c = 1 - \frac{g^2}{2m^2gl} = \cos \theta_m$$

The whole thing can be captured in a diagram:



Summary: String crumples at angle  $\theta_c$  given by

$$\cos \theta_c = \frac{p/a}{m} \left( 1 - \frac{g^2}{2m^2gl} \right), \quad \frac{\pi}{2} < \theta_c < \pi$$

when

$$1 < \frac{g^2}{2m^2gl} < \frac{p/a}{m}$$