

Phys 522

Homework #1

Solution Set

1.1. C-T B<sub>ix</sub>. 1

$$(a) \quad 1 = \langle \psi | \psi \rangle = \int d^3r (|\psi_+(r)|^2 + |\psi_-(r)|^2)$$

$$= \int r^2 dr |R(r)|^2 \int d\Omega \left( |Y_0^0 + \frac{1}{\sqrt{3}} Y_1^0|^2 + \frac{1}{3} |Y_1^1 - Y_1^{-1}|^2 \right)$$

Use orthogonality of  $Y_0^0$  and  $Y_1^0$  and of  $Y_1^1$  and  $Y_1^{-1}$ .

$$\rightarrow = \int d\Omega \left( |Y_0^0|^2 + \frac{1}{3} |Y_1^0|^2 + \frac{1}{3} |Y_1^1|^2 + \frac{1}{3} |Y_1^{-1}|^2 \right)$$

$$= \frac{4}{3} + \frac{4}{3} \quad \left. \begin{array}{l} \text{from } - \\ \text{from } + \end{array} \right\}$$

$$1 = R \int dr r^2 |R(r)|^2$$

$$\int_0^\infty dr r^2 |R(r)|^2 = \frac{1}{R}$$

(b)

Measure  $S_z$ : possible values  $\pm \hbar/2$ .

$$P(S_z = \pm \hbar/2) = \int d^3r |\langle \vec{r}, \pm | \psi \rangle|^2 = \int d^3r |\psi_{\pm}(\vec{r})|^2 = \frac{1}{R}$$

$$P(S_z = +\hbar/2) = \int d^3r |\psi_+(\vec{r})|^2 = \frac{4}{3R}$$

$$P(S_z = -\hbar/2) = \int d^3r |\psi_-(\vec{r})|^2 = \frac{1}{3R}$$

Measure  $L_z$ : possible values  $0, \hbar$  (with non-zero probability)

(2)

$$P(L_z = m\hbar) = \sum_{\pm} \sum_{l=0}^{\infty} \int dr \underbrace{P(r, l, m, \pm)}_{dr r^2 |\langle r, l, m, \pm | \psi \rangle|^2}$$

$$P(m=0) = \underbrace{\int dr r^2 |R(r)|^2}_{l=0, m=0, +} + \underbrace{\int dr r^2 \frac{1}{3} |R(r)|^2}_{l=1, m=0, +} + \int dr r^2 \frac{1}{3} |R(r)|^2_{l=1, m=0, -}$$

$$P(L_z = 0) = \frac{1}{6}$$

$$P(m=0) = \underbrace{\int dr r^2 \frac{1}{3} |R(r)|^2}_{l=1, m=0, -} = \frac{1}{6} = P(L_z = \hbar)$$

Measure  $S_x$ : possible values  $\pm \frac{1}{2} \hbar$

$$|\psi\rangle = \int d^3r \left( |\vec{r}\rangle \otimes |+\rangle_z \psi_+(\vec{r}) + |\vec{r}\rangle \otimes |-\rangle_z \psi_-(\vec{r}) \right)$$

$$P(S_x = \pm \hbar/2) = \int d^3r |\langle \vec{r} | \otimes \langle \pm |) |\psi\rangle|^2$$

$$|+\rangle_x = \frac{1}{\sqrt{2}} (|+\rangle_z + |-\rangle_z)$$

$$|-\rangle_x = \frac{1}{\sqrt{2}} (|+\rangle_z - |-\rangle_z)$$

$$\langle \vec{r} | S_x = +\hbar | \psi \rangle = \frac{1}{\sqrt{2}} (\langle \vec{r} | +1 \rangle + \langle \vec{r} | -1 \rangle | \psi \rangle)$$

$$= \frac{1}{\sqrt{2}} (\psi_+(r) + \psi_-(r))$$

$$= \frac{1}{\sqrt{2}} R(r) \left( Y_0^0 + \frac{1}{\sqrt{3}} Y_1^0 \right)$$

$$\langle \vec{r} | S_x = -\hbar | \psi \rangle = \frac{1}{\sqrt{2}} (-\langle \vec{r} | +1 \rangle + \langle \vec{r} | -1 \rangle | \psi \rangle)$$

$$= \frac{1}{\sqrt{2}} (-\psi_+(r) + \psi_-(r))$$

$$= \frac{1}{\sqrt{2}} R(r) \left( -Y_0^0 + \frac{1}{\sqrt{3}} Y_1^0 - \frac{2}{\sqrt{3}} Y_1^0 \right)$$

$$P(S_x = +\hbar | r) = \int r^2 dr \frac{1}{r^2} |R(r)|^2 \left( 1 + \frac{1}{3} \right) = \boxed{\frac{4}{3} P(S_x = +\hbar | r)}$$

$$P(S_x = -\hbar | r) = \int r^2 dr \frac{1}{r^2} |R(r)|^2 \left( 1 + \frac{1}{3} + \frac{4}{3} \right)$$

$$= \boxed{\frac{8}{3} P(S_x = -\hbar | r)}$$

(b) Measure  $L^2$  (0)

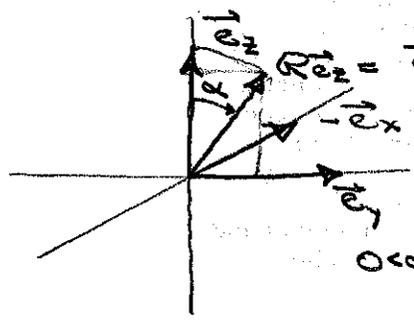
(i) Get result  $L^2 = 0$ ; state immediately after has

$\psi_+^1(\vec{r}) = C R(r) Y_0^0$	normalization
$\psi_-^1(\vec{r}) = 0$	

(2) Get result  $L^2 = 2h^2 (l=1)$ ; state immediately after has ④

$$\psi_+^{(1)}(x) = C D \sqrt{\frac{1}{2\pi}} Y_1^0$$
$$\psi_-^{(1)}(x) = \underbrace{C D \sqrt{\frac{1}{2\pi}}}_{\text{normalization}} (Y_1^1 - Y_1^0)$$

1.2.



$$\vec{u} = \vec{e}_x \cos \alpha + \vec{e}_y \sin \alpha \Rightarrow \begin{matrix} 0 < \alpha < \pi & \theta = \alpha \\ \pi < \alpha < 2\pi & \theta = \pi - \alpha \end{matrix}$$

$$\phi = \pi/2 \quad \phi = 3\pi/2$$

$$0 < \alpha < \pi: \begin{aligned} |+\rangle_{\vec{u}} &= \cos(\alpha/2) |+\rangle_{\vec{z}} + i \sin(\alpha/2) |-\rangle_{\vec{z}} \\ |-\rangle_{\vec{u}} &= \sin(\alpha/2) |+\rangle_{\vec{z}} - i \cos(\alpha/2) |-\rangle_{\vec{z}} \end{aligned}$$

$$\pi < \alpha < 2\pi: \begin{aligned} |+\rangle_{\vec{u}} &= -\cos(\alpha/2) |+\rangle_{\vec{z}} - i \sin(\alpha/2) |-\rangle_{\vec{z}} \\ |-\rangle_{\vec{u}} &= \sin(\alpha/2) |+\rangle_{\vec{z}} + i \cos(\alpha/2) |-\rangle_{\vec{z}} \end{aligned}$$

$$R = e^{i\alpha S_x/\hbar} = e^{i\alpha_x \alpha/2} \cdot \cos(\alpha/2) \mathbb{1} + i \sin(\alpha/2) \sigma_x$$

$$\begin{aligned} R |e\rangle_{\vec{z}} &= (\cos(\alpha/2) \mathbb{1} + i \sin(\alpha/2) \sigma_x) |e\rangle_{\vec{z}} \\ &= \cos(\alpha/2) |e\rangle_{\vec{z}} + i \sin(\alpha/2) \sigma_x |e\rangle_{\vec{z}} \\ &= \cos(\alpha/2) |e\rangle_{\vec{z}} + i \sin(\alpha/2) |-e\rangle_{\vec{z}} \end{aligned}$$

$\sigma_x \rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$   
 in  $|e\rangle_{\vec{z}}$  basis  
 $\sigma_x |+\rangle_{\vec{z}} = |-\rangle_{\vec{z}}$   
 $\sigma_x |-\rangle_{\vec{z}} = |+\rangle_{\vec{z}}$   
 $\Rightarrow \sigma_x |e\rangle_{\vec{z}} = |-e\rangle_{\vec{z}}$

$$R |+\rangle_{\vec{z}} = \cos(\alpha/2) |+\rangle_{\vec{z}} + i \sin(\alpha/2) |-\rangle_{\vec{z}}$$

$$R |-\rangle_{\vec{z}} = \cos(\alpha/2) |-\rangle_{\vec{z}} + i \sin(\alpha/2) |+\rangle_{\vec{z}}$$

$$0 < \alpha < \pi: \begin{aligned} R |+\rangle_{\vec{z}} &= |+\rangle_{\vec{u}}, & R |-\rangle_{\vec{z}} &= i |-\rangle_{\vec{u}} \\ \delta_+ &= 0, & \delta_- &= \pi/2 \end{aligned}$$

$$\pi < \alpha < 2\pi: \begin{aligned} R |+\rangle_{\vec{z}} &= -|+\rangle_{\vec{u}}, & R |-\rangle_{\vec{z}} &= i |-\rangle_{\vec{u}} \\ \delta_+ &= \pi, & \delta_- &= \pi/2 \end{aligned}$$

The phase discontinuities at  $\alpha=0$  and  $\alpha=\pi$  and the fact that  $R(2\pi)$  appears not to be  $-1$  are both expressions of the coordinate singularities at the poles of the Bloch sphere, here appearing as singularities in the phases of the eigenvectors.

1.3. Show

$$R_{\vec{u}}^+(\alpha) \vec{J} R_{\vec{u}}(\alpha) = \vec{u}(\vec{u} \cdot \vec{J}) + \vec{u} \times (\vec{u} \times \vec{J}) \cos \alpha + \vec{u} \times \vec{J} \sin \alpha$$

(a) Use commutators:

$$R_{\vec{u}}^+ \vec{J} R_{\vec{u}} = e^{+i \vec{J} \cdot \vec{u} \alpha / \hbar} \vec{J} e^{-i \vec{J} \cdot \vec{u} \alpha / \hbar}$$

$$\begin{aligned} \text{Use } e^A B e^{-A} &= B + [A, B] + \frac{1}{2!} [A, [A, B]] + \dots \\ &= B + \sum_{k=1}^{\infty} \frac{1}{k!} \underbrace{[A, [A, \dots [A, B] \dots]]}_{k \text{ nested commutators}} \end{aligned}$$

$$[A, J_j] = \frac{i}{\hbar} \alpha u_k \underbrace{[J_k, J_j]}_{i \hbar \epsilon_{kjl} J_l} = + \alpha \epsilon_{jkl} u_k J_l = \alpha (\vec{u} \times \vec{J})_j$$

$$\Rightarrow [A, \vec{J}] = \vec{e}_j [A, J_j] = \alpha \vec{u} \times \vec{J}$$

$$[A, \vec{J}]^{(2)} = [A, [A, \vec{J}]] = [A, \alpha \vec{u} \times \vec{J}] = \alpha \vec{u} \times [A, \vec{J}] = \alpha \vec{u} \times (\alpha \vec{u} \times \vec{J})$$

$$\Rightarrow [A, \vec{J}]^{(2)} = \alpha^2 \vec{u} \times (\vec{u} \times \vec{J}) = \alpha^2 \vec{u} (\vec{u} \cdot \vec{J}) - \alpha^2 \vec{J}$$

$$[A, \vec{J}]^{(3)} = [A, [A, \vec{J}]^{(2)}] = \alpha^3 \vec{u} \times (\vec{u} \times (\vec{u} \times \vec{J})) = -\alpha^3 \vec{u} \times \vec{J}$$

The pattern is now established:

$$k > 0: [A, \vec{J}]^{(k)} = \begin{cases} (-1)^{(k-1)/2} \alpha^k \vec{u} \times \vec{J}, & k \text{ odd} \\ (-1)^{(k-2)/2} \alpha^k \vec{u} \times (\vec{u} \times \vec{J}), & k \text{ even} \end{cases}$$

$$R^{\dagger} \vec{J} R = \vec{J} + \sum_{k=1}^{\infty} \frac{1}{k!} [A, \vec{J}]^{(k)}$$

$$= \vec{J} + \vec{u} \times \vec{J} \sum_{k \text{ odd}} \frac{(-1)^{(k-1)/2}}{k!} \alpha^k$$

$$+ \vec{u} \times (\vec{u} \times \vec{J}) \sum_{\substack{k \text{ even} \\ k \geq 2}} \frac{(-1)^{(k-2)/2}}{k!} \alpha^k$$

$$k = 2l+1: \sum_{l=0}^{\infty} \frac{(-1)^l}{(2l+1)!} \alpha^{2l+1} = \sin \alpha$$

$$k = 2l: \sum_{l=1}^{\infty} \frac{(-1)^{l-1}}{(2l)!} \alpha^{2l} = 1 - \sum_{l=0}^{\infty} \frac{(-1)^l}{(2l)!} \alpha^{2l}$$

$$= 1 - \cos \alpha$$

$$\therefore R^{\dagger} \vec{J} R = \vec{J} + \underbrace{\vec{u} \times (\vec{u} \times \vec{J})}_{\vec{u}(\vec{u} \cdot \vec{J}) - \vec{J}}$$

$$= \vec{u}(\vec{u} \cdot \vec{J}) - \vec{u} \times (\vec{u} \times \vec{J}) \cos \alpha + \vec{u} \times \vec{J} \sin \alpha$$

This method only uses the commutators,

$[J_j, J_k] = i \epsilon_{jkl} J_l$ , so if we can establish

the property for the spin vector  $\vec{J} = \frac{1}{2} \hbar \vec{\sigma}$ , which

has the angular-momentum commutators, then it

will be true for any operators  $J_j$ .

$[J_j, J_k] = i \epsilon_{jkl} J_l$

(b) Use  $R = e^{-i\vec{S}\cdot\vec{u}\alpha/\hbar} = e^{-i\vec{\sigma}\cdot\vec{u}\alpha/2} = 1 \cos(\alpha/2) - i\vec{\sigma}\cdot\vec{u} \sin(\alpha/2)$ .

$$\vec{\sigma}\cdot\vec{R} = \sigma_j c - i \underbrace{\sigma_j \sigma_k u_k}_{\delta_{jk} + i\epsilon_{jkl}\sigma_l} s = \sigma_j c - i u_j s + \epsilon_{jkl} u_k \sigma_l s$$

$$\vec{\sigma}\cdot\vec{R} = \vec{\sigma}\cdot\vec{c} - i\vec{u}\cdot\vec{s} + \vec{u}\times\vec{s}$$

$$R^\dagger \vec{\sigma}\cdot\vec{R} = (1c + i u_m \sigma_m s) (\sigma_j c - i u_j s + \epsilon_{jkl} u_k \sigma_l s)$$

$$= \sigma_j c^2 - i u_j c s + \epsilon_{jkl} u_k \sigma_l s c$$

$$+ i s c u_m \sigma_m \sigma_j + s^2 u_j u_m \sigma_m + i s^2 \underbrace{\epsilon_{jkl} u_k \sigma_m \sigma_l u_m}_{\delta_{mj} + i\epsilon_{mjl}\sigma_l}$$

$$= \sigma_j c^2 - i u_j c s + \epsilon_{jkl} u_k \sigma_l s c$$

$$+ i u_j s c + \epsilon_{jml} u_m \sigma_l s c$$

$$+ u_j u_m \sigma_m s^2$$

$$+ i s^2 \epsilon_{jkl} u_k u_l s^2 + \epsilon_{jkl} \epsilon_{lmn} u_k u_m \sigma_n s^2$$

$$= \frac{1}{2} \sigma_j (1 + \cos\alpha) + \epsilon_{jkl} u_k \sigma_l \sin\alpha$$

$$+ u_j u_k \sigma_k \frac{1}{2} (1 - \cos\alpha)$$

$$+ \epsilon_{jkl} u_k \epsilon_{lmn} u_m \sigma_n \frac{1}{2} (1 - \cos\alpha)$$

$$R^\dagger \vec{\sigma}\cdot\vec{R} = \frac{1}{2} \vec{\sigma} (1 + \cos\alpha) + \vec{u}\times\vec{\sigma} \sin\alpha$$

$$+ \vec{u}(\vec{u}\cdot\vec{\sigma}) \frac{1}{2} (1 - \cos\alpha)$$

$$+ \vec{u}\times(\vec{u}\times\vec{\sigma}) \frac{1}{2} (1 - \cos\alpha) \rightarrow \vec{u}(\vec{u}\cdot\vec{\sigma}) - \vec{\sigma}$$

$$= \frac{1}{r} \vec{\sigma} (1 + \cos \alpha) + \vec{u} \times \vec{\sigma} \sin \alpha$$

$$+ \vec{u} (\vec{u} \cdot \vec{\sigma}) (1 - \cos \alpha) - \vec{\sigma} \frac{1}{r} (1 - \cos \alpha)$$

$$= \vec{\sigma} \cos \alpha + \vec{u} (\vec{u} \cdot \vec{\sigma}) (1 - \cos \alpha) + \vec{u} \times \vec{\sigma} \sin \alpha$$

$$\boxed{R^{\dagger} \vec{\sigma} R = \vec{u} (\vec{u} \cdot \vec{\sigma}) - \vec{u} \times (\vec{u} \times \vec{\sigma}) \cos \alpha + \vec{u} \times \vec{\sigma} \sin \alpha}$$

1.4. C-T  $B_{ix} \cdot \mathbb{R}$

$$A = \vec{S} \cdot \vec{P} = S_x P_x + S_y P_y + S_z P_z = \frac{1}{2} \hbar \vec{\sigma} \cdot \vec{P}$$

$$(a) \quad A^\dagger = \vec{P}^\dagger \cdot \vec{S}^\dagger = \vec{P} \cdot \vec{S} = \vec{S} \cdot \vec{P} = A$$

$\uparrow$   
 $\vec{P}$  and  $\vec{S}$  Hermitian

$\swarrow$   
 $\vec{P}$  and  $\vec{S}$  commute

$\Rightarrow$  A is Hermitian.

(b)  $[A, P_j] = 0$  because  $P_j$  commutes w/ all components of  $\vec{P}$  and  $\vec{S}$ .  $\therefore \exists$  a simultaneous eigenbasis of  $P_x, P_y, P_z$ , and  $A$ .

$$\text{Let } |\vec{p}, \epsilon\rangle = |P_x, P_y, P_z, \epsilon\rangle \equiv |\vec{p}\rangle \otimes |\epsilon\rangle_{\mathbb{Z}}$$

$$A |\vec{p}, \epsilon\rangle = \frac{1}{2} \hbar \vec{\sigma} \cdot \vec{P} |\vec{p}, \epsilon\rangle = \frac{1}{2} \hbar |\vec{p}\rangle \otimes (\vec{p} \cdot \vec{\sigma}) |\epsilon\rangle_{\mathbb{Z}}$$

In the 2-dimensional subspace spanned by  $|\vec{p}, +\rangle$  and  $|\vec{p}, -\rangle$ ,  $A$  acts like

$$\frac{1}{2} \hbar \vec{P} \cdot \vec{\sigma} = \frac{1}{2} \hbar (P_x \sigma_x + P_y \sigma_y + P_z \sigma_z),$$

which in the  $|\pm\rangle_{\mathbb{Z}}$  basis has the matrix representation

$$\frac{1}{2} \hbar \left[ P_x \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + P_y \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + P_z \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right]$$

$$= \frac{1}{2} \hbar \begin{pmatrix} P_z & P_x - iP_y \\ P_x + iP_y & -P_z \end{pmatrix}$$

(c) The essential task is to diagonalize  $\frac{1}{2}\hbar\vec{p}\cdot\vec{\sigma}$  in the 2-dimensional subspace spanned by  $|\vec{p}, \pm\rangle$ . But this is trivial. The eigenvectors are  $| \pm \rangle_{\vec{u}}$ , where  $\vec{p} = |\vec{p}|\vec{u}$ , with corresponding eigenvalues  $\pm \frac{1}{2}\hbar|\vec{p}|$ . Formally we can write

$$\begin{aligned}
 A &= \frac{1}{2}\hbar\vec{p}\cdot\vec{\sigma} \\
 &= \int d^3p \frac{1}{2}\hbar\vec{p}\cdot\vec{\sigma} |\vec{p}\rangle\langle\vec{p}| \\
 &= \int d|\vec{p}| d\Omega_{\vec{u}} \frac{1}{2}\hbar|\vec{p}|\vec{u}\cdot\vec{\sigma} |\vec{p}\rangle\langle\vec{p}| \\
 &\quad \left( |+\rangle_{\vec{u}}\langle+| - |-\rangle_{\vec{u}}\langle-| \right)
 \end{aligned}$$

$$\begin{aligned}
 A &= \int d|\vec{p}| d\Omega_{\vec{u}} \left( \frac{1}{2}\hbar|\vec{p}| |\vec{p}\rangle\langle\vec{p}| \otimes |+\rangle_{\vec{u}}\langle+|_{\vec{u}} - \frac{1}{2}\hbar|\vec{p}| |\vec{p}\rangle\langle\vec{p}| \otimes |-\rangle_{\vec{u}}\langle-|_{\vec{u}} \right)
 \end{aligned}$$

Eigenvectors:  $|\vec{p}\rangle \otimes |+\rangle_{\vec{u}}$

$|\vec{p}\rangle \otimes |-\rangle_{\vec{u}}$

Eigenvalues:  $\frac{1}{2}\hbar|\vec{p}|$

$-\frac{1}{2}\hbar|\vec{p}|$

Each eigenvalue is degenerate over a sphere in momentum space.