

Ph 452 Lecture 19

101 quick review

$$\text{States: } |\psi\rangle \rightarrow \rho = \sum \lambda_i |\psi_i\rangle \langle \psi_i|$$

$$\text{tr } \rho = 1, \rho = \rho^\dagger, \rho \geq 0$$

Dynamics:

$$\begin{aligned} |\psi\rangle \rightarrow U|\psi\rangle \\ \langle \psi| \rightarrow \langle \psi|U \end{aligned} \} \Rightarrow \rho = \sum \lambda_i |\psi_i\rangle \langle \psi_i| \\ \rightarrow \sum \lambda_i U|\psi_i\rangle \langle \psi_i|U^\dagger \\ = U\rho U^\dagger$$

Measurement:

$$\begin{aligned} |\psi\rangle \rightarrow \frac{\Pi_k |\psi\rangle}{\sqrt{\text{prob}(k)}} \Rightarrow \rho = \sum \lambda_i |\psi_i\rangle \langle \psi_i| \\ \rightarrow \frac{\sum \lambda_i \Pi_k |\psi_i\rangle \langle \psi_i| \Pi_k}{\text{prob}(k)} \end{aligned}$$

But  $\text{prob}(k) = \text{tr}(\Pi_k \rho)$ , so

$$\rho \rightarrow \frac{\Pi_k \rho \Pi_k}{\text{tr}(\Pi_k \rho)} \quad \text{w/ prob } \text{tr}(\Pi_k \rho) \quad \text{"conditional evolution"}$$

Discarding outcome label  $\rightarrow$  get an ensemble average!

$$\rho \rightarrow \sum \text{prob}(k) \frac{\Pi_k \rho \Pi_k}{\text{tr}(\Pi_k \rho)} = \sum \Pi_k \rho \Pi_k$$

"Unconditional evolution"



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Unitarity demands

$$\sum_k A_k^\dagger A_k = \sum_k \langle \psi | U_{AB}^\dagger |k\rangle \langle k| U_{AB} | \psi \rangle$$

$$= \langle \psi | U_{AB}^\dagger U_{AB} | \psi \rangle$$

$$\sum_k A_k^\dagger A_k = I$$

More general evolution?

(a) Initial state may be entangled:

Deciding is an NP problem.

Def: A state  $\rho$  is entangled if it cannot be written as

$$\rho = \sum_i \lambda_i \rho_A^i \otimes \rho_B^i$$

Otherwise it is separable.

Example:  $\rho = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle) \langle \frac{1}{\sqrt{2}}(\langle 00| + \langle 11|) =$

$$= \frac{1}{2} (|00\rangle\langle 00| + |00\rangle\langle 11| + |11\rangle\langle 00| + |11\rangle\langle 11|)$$

$$= \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ is entangled.}$$

(b) Could have conditional evolution via a measurement  $\{\Pi_{AB}^i\}$  after  $U_{AB}^i$ . (More on this later.)

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General map  $\rho \mapsto \rho' = \mathcal{A}(\rho)$  desiderata

"Convex linear"

(a) Convex-linear:  $\mathcal{A}(\lambda \rho_1 + (1-\lambda) \rho_2) = \lambda \mathcal{A}(\rho_1) + (1-\lambda) \mathcal{A}(\rho_2) \quad 0 \leq \lambda \leq 1$

(Preserves ensemble interpretation)  $\Rightarrow$  can extend to linear map

(b) Hermiticity-preserving:  $\rho = \rho^\dagger \Rightarrow \rho' = \rho'^\dagger$

(c) Trace-preserving:  $\text{tr} \rho = 1 \Rightarrow \text{tr} \rho' = 1$

(d) Positive ("positivity preserving")  $\rho \geq 0 \Rightarrow \rho' \geq 0$  (non-neg. eigenvalues)

Note:  $\mathcal{A} \otimes I$  is trace-preserving & linear

(e) Completely positive:  $\mathcal{A} \otimes I_B$  is positive for all systems B.

Transpos. map: Not CP

Note (e)  $\Rightarrow$  (d) and (d)  $\Rightarrow$  (b)

So Completely Positive Trace-preserving map (CPTP) map

Kraus Representation Theorem: Every CPTP map has an OSR

Proof: See Preskill's notes §3.3 or Thm 8.1 in N+C

Skip: Jamil Karim Isomorphism

Ambiguity in the OSR:

$\mathcal{A}(\rho) = \sum_{k=1}^m A_k \rho A_k^\dagger, \quad \mathcal{B}(\rho) = \sum_{k=1}^n B_k \rho B_k^\dagger$

$\mathcal{A} = \mathcal{B} \Rightarrow A_j = \sum U_{jk} B_k$  where  $U_{jk}$  is an  $m \times n$  matrix

(append "zero" Kraus ops to smaller list)

Get this far