

# Physics 405: Lecture 25

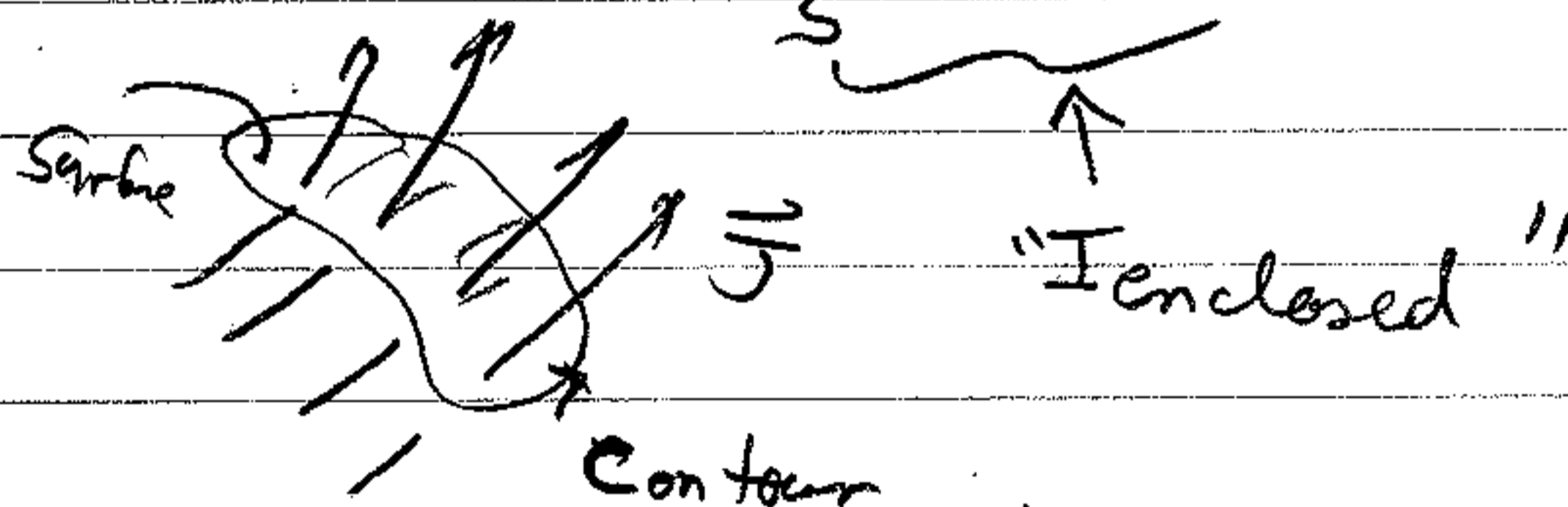
## Ampere's Law

The fundamental equations of magneto-statics:

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

• In integral form  $\Rightarrow \oint_S \vec{B} \cdot d\vec{a} = 0$  flux of  $\vec{B}$  through closed surface is zero

•  $\int (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} = \mu_0 \int_S \vec{J} \cdot d\vec{a}$



Stokes theorem  $\int_S (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} = \oint_C \vec{B} \cdot d\vec{l}$   
(C right hand rule)

$$\Rightarrow \oint_C \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed}}$$

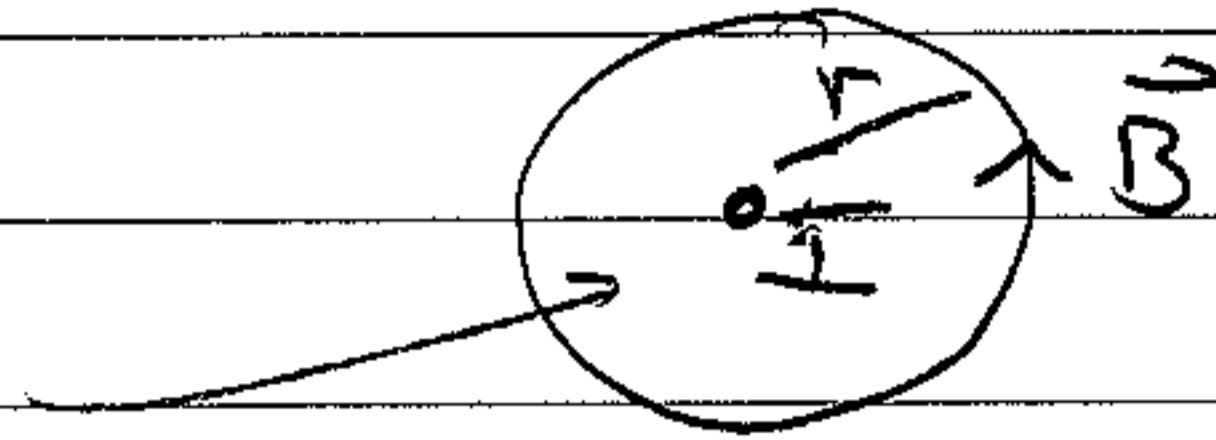
Integral form of Ampere's Law.

Like Gauss's Law in electrostatics, in symmetrical situations, it's the best way to find  $\vec{B}$ .

Canonical example: Infinite wire, current I

Symmetry and  $\nabla \cdot \vec{B} = 0$

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$$\Rightarrow \vec{B} = B(r) \hat{\phi}$$

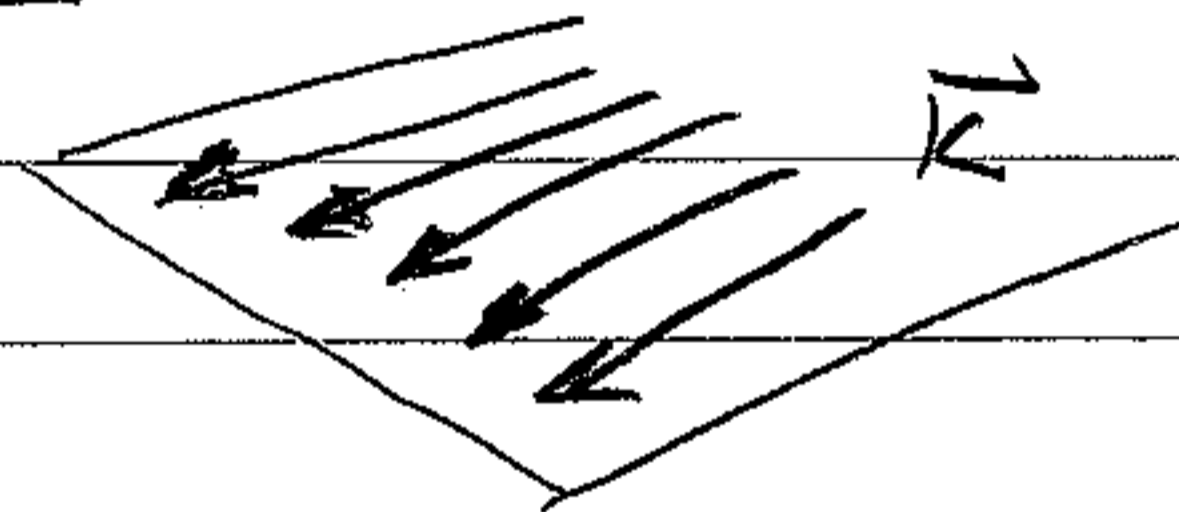
Choose contour along  $\vec{B}$

$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = \oint B(r) dl$$

$$= B(r) \oint dl = 2\pi r B(r)$$

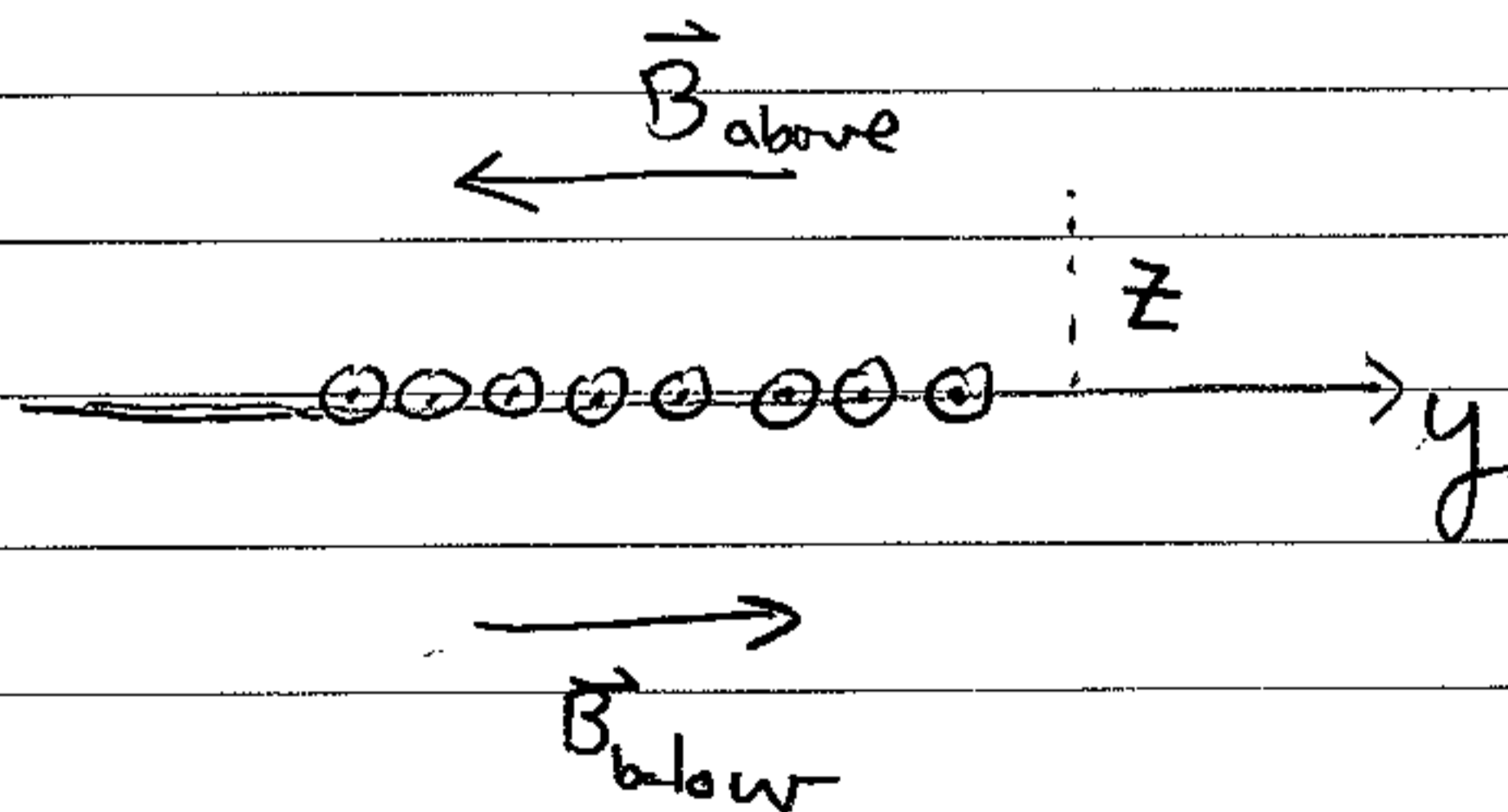
$$I_{enc} = I \Rightarrow B(r) = \frac{\mu_0 I}{2\pi r}$$

Example Current Sheet



Uniform current on infinite plane  
Let  $\vec{K} = K \hat{x}$

Edge-on

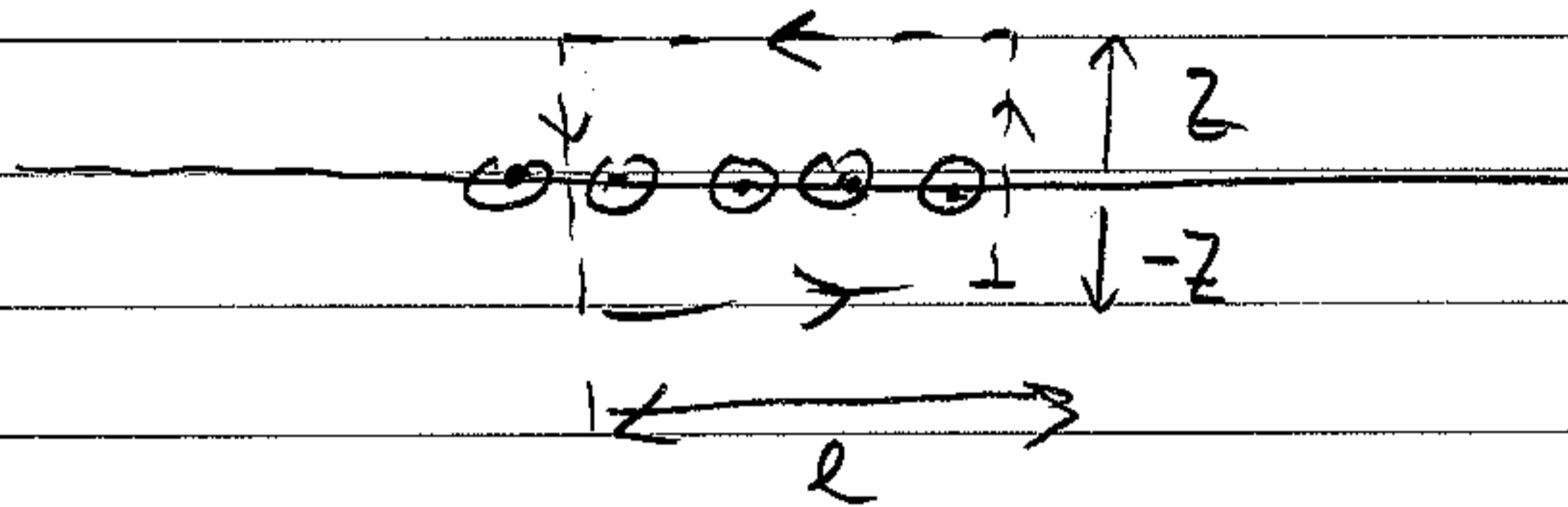


By symmetry and R.H.R  $\vec{B} = B(z) \hat{y}$

$$B(z) = -B(-z)$$

$|\vec{B}|$  independent of x and y

## Amperean Loop

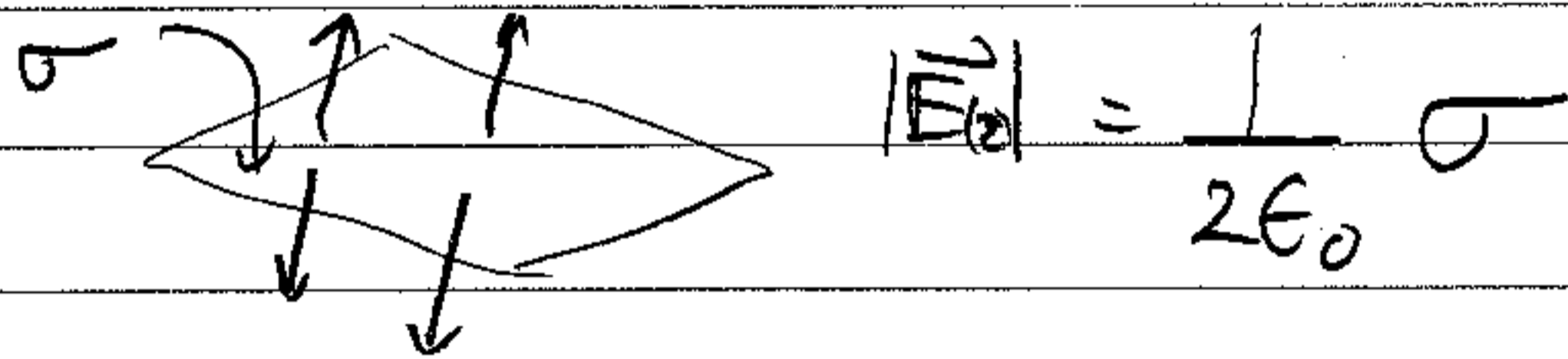


$$\oint \vec{B} \cdot d\vec{l} = 2l |\vec{B}(z)| = \mu_0 I_{\text{enc}}$$

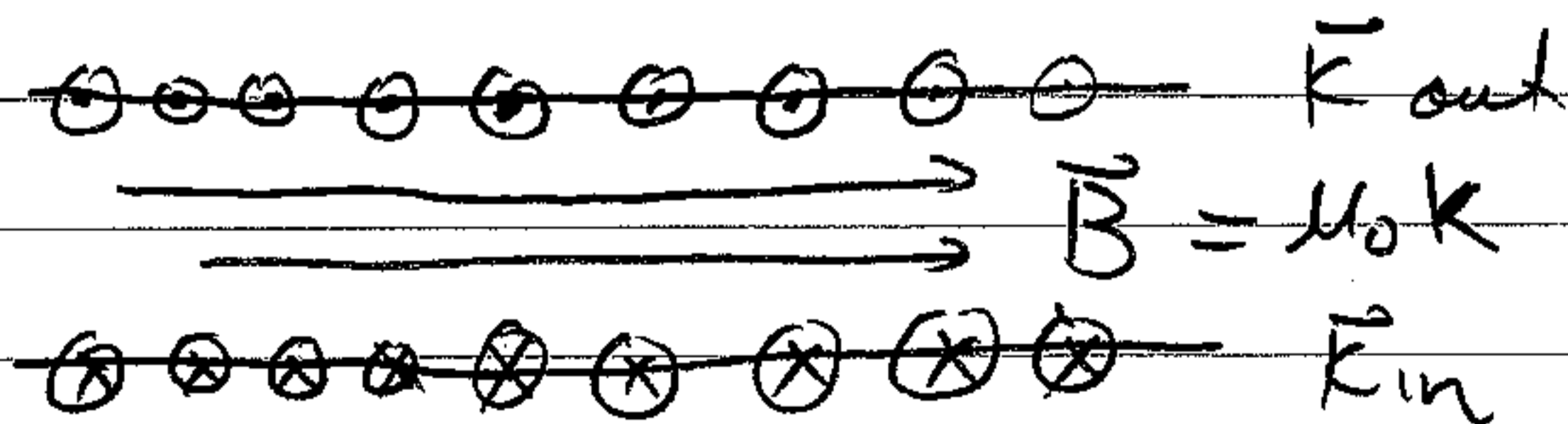
"  $Kl$

$$\Rightarrow |\vec{B}(z)| = \frac{\mu_0 K}{2} \text{ independent of } z$$

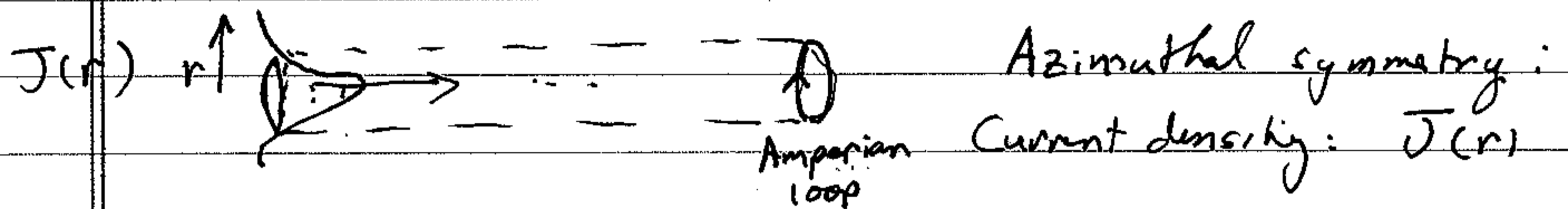
Analogous:  $\vec{E}$ -field of plane of charge:



Two planes of current (equal opposite)



Example: Cylindrical current "beam"



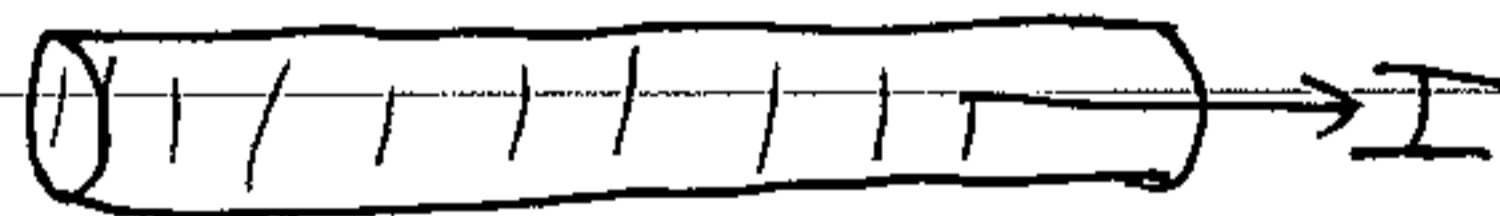
Symmetry  $\Rightarrow \vec{B} = B(r) \hat{\phi}$

$$\oint \vec{B} \cdot d\vec{\ell} = (2\pi r) B(r) = \mu_0 I_{enc}(r)$$

$$\Rightarrow B(r) = \frac{\mu_0 I_{enc}(r)}{2\pi r} = \frac{\mu_0 \int_0^r J(r') 2\pi r' dr'}{2\pi r}$$

Examples: ~~the~~

- Uniform current in a pipe, radius R

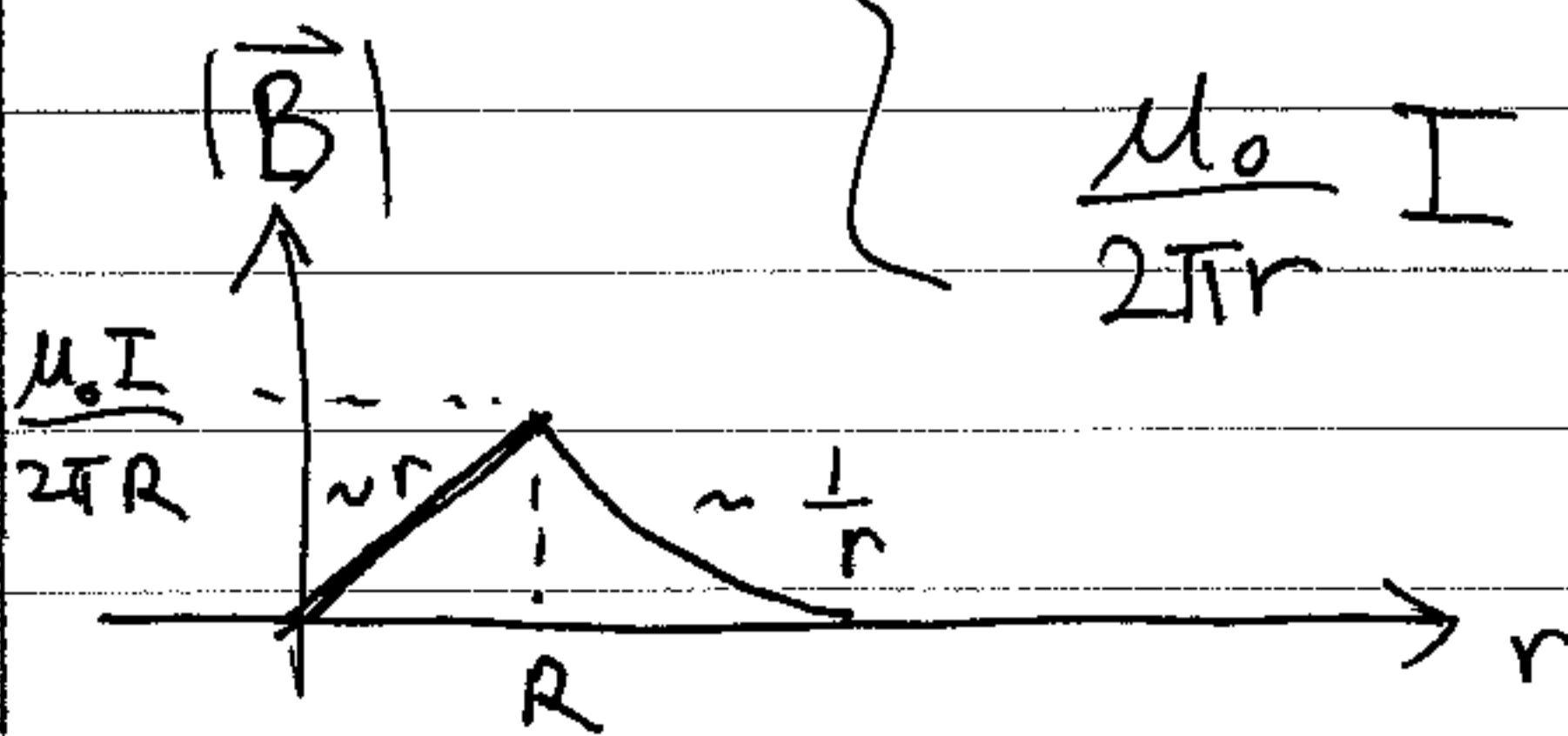


$$\Rightarrow J = \begin{cases} \frac{I}{\pi R^2} & r < R \\ 0 & r > R \end{cases}$$

~~$\Rightarrow B(r) = \dots$~~

$$I_{enc}(r) = \begin{cases} \pi r^2 J = \left(\frac{r}{R}\right)^2 I & r < R \\ I & r > R \end{cases}$$

$$\therefore B(r) = \begin{cases} \frac{\mu_0 r I}{2\pi R^2} & r < R \\ \frac{\mu_0 I}{2\pi r} & r > R \end{cases}$$



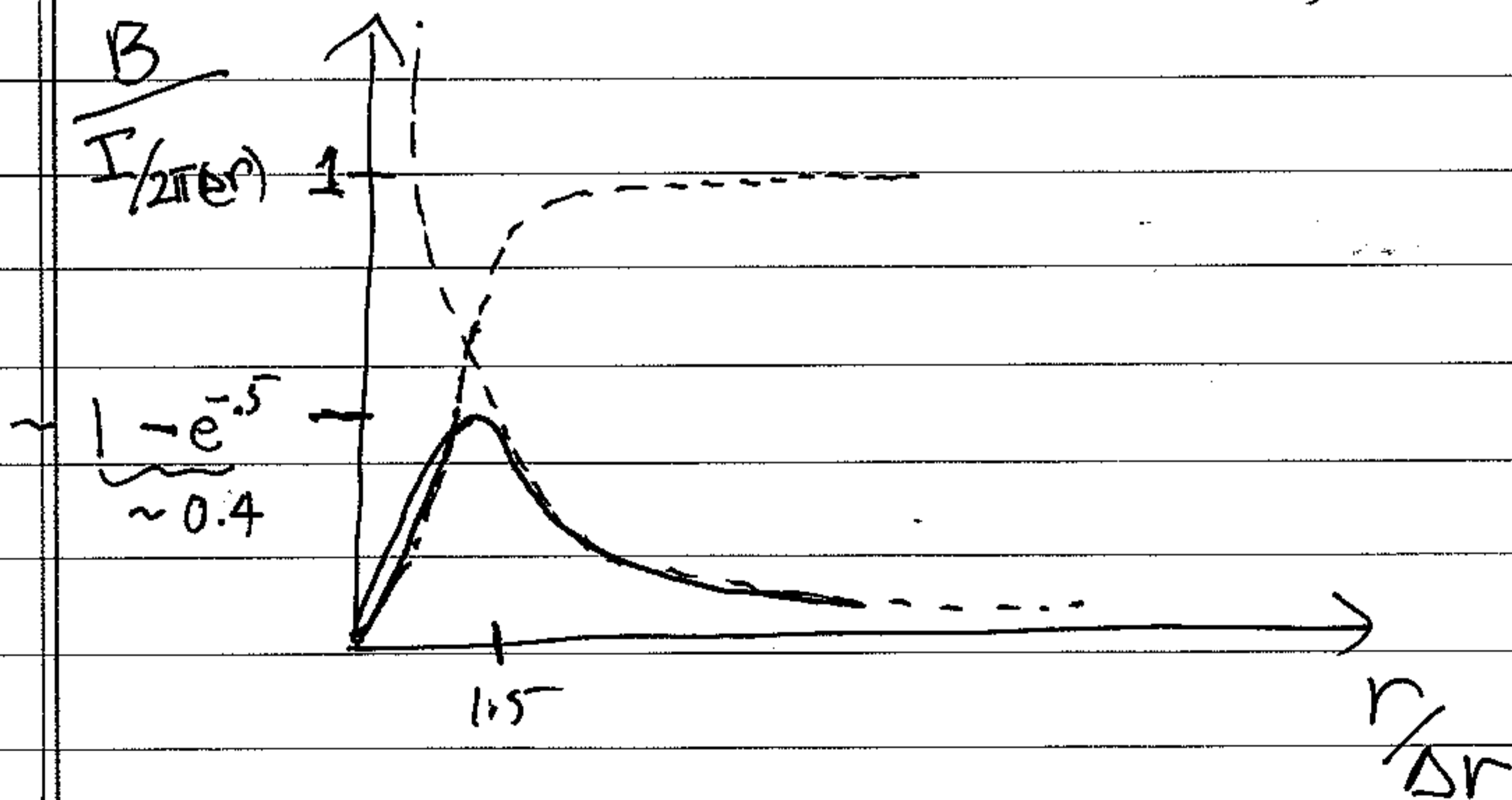
Gaussian beam:  $J(r) = \frac{I}{2\pi(\Delta r)^2} e^{-\frac{r^2}{2(\Delta r)^2}}$

$$\int_0^{\infty} J(r) 2\pi r' dr' = I$$

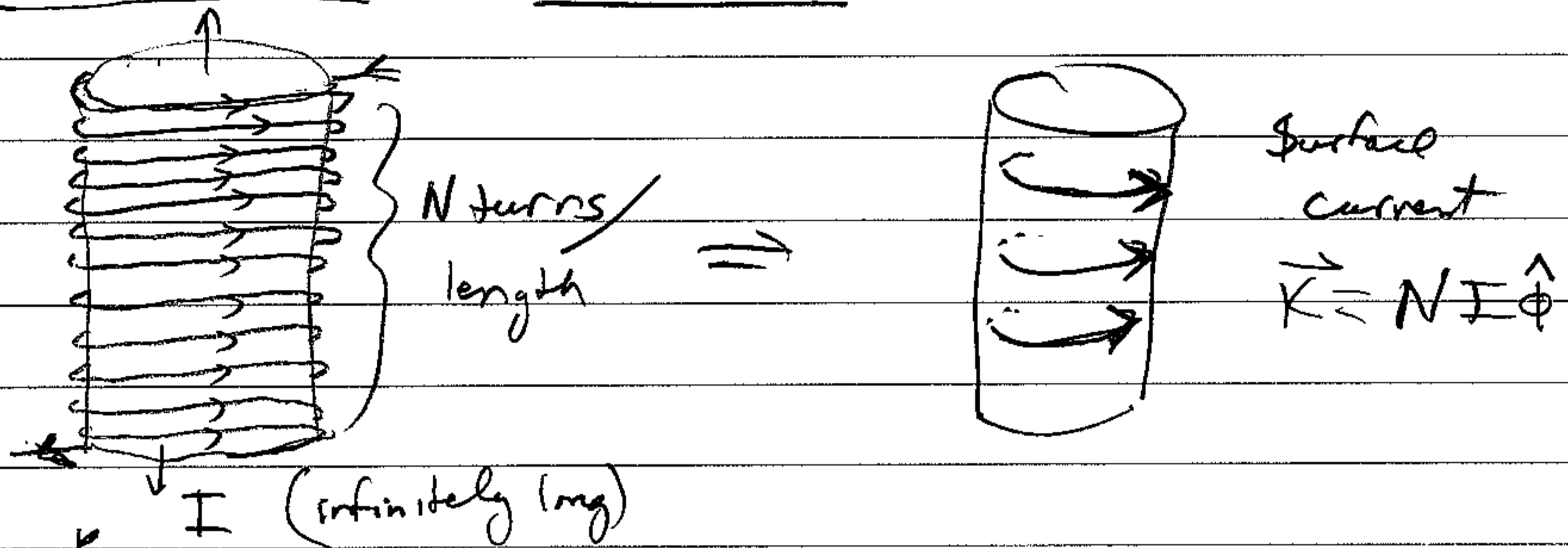
$$\begin{aligned} \Rightarrow I_{enc}(r) &= \int_0^r J(r') 2\pi r' dr' = \\ &= \frac{I}{(\Delta r)^2} \int_0^r r' e^{-\frac{r'^2}{2(\Delta r)^2}} dr' \\ &= \frac{I}{(\Delta r)^2} \left(1 - e^{-\frac{r^2}{2(\Delta r)^2}}\right) \end{aligned}$$

$$\Rightarrow I_{enc}(r) = I \left(1 - e^{-\frac{r^2}{2(\Delta r)^2}}\right)$$

$$\therefore B(r) = \frac{I}{2\pi r} \left(1 - e^{-\frac{r^2}{2(\Delta r)^2}}\right)$$



## Important Example: The Solenoid



Direction of  $\vec{B}$ ?

Cylindrical components:  $\vec{B} = B_r \hat{r} + B_\phi \hat{\phi} + B_z \hat{z}$

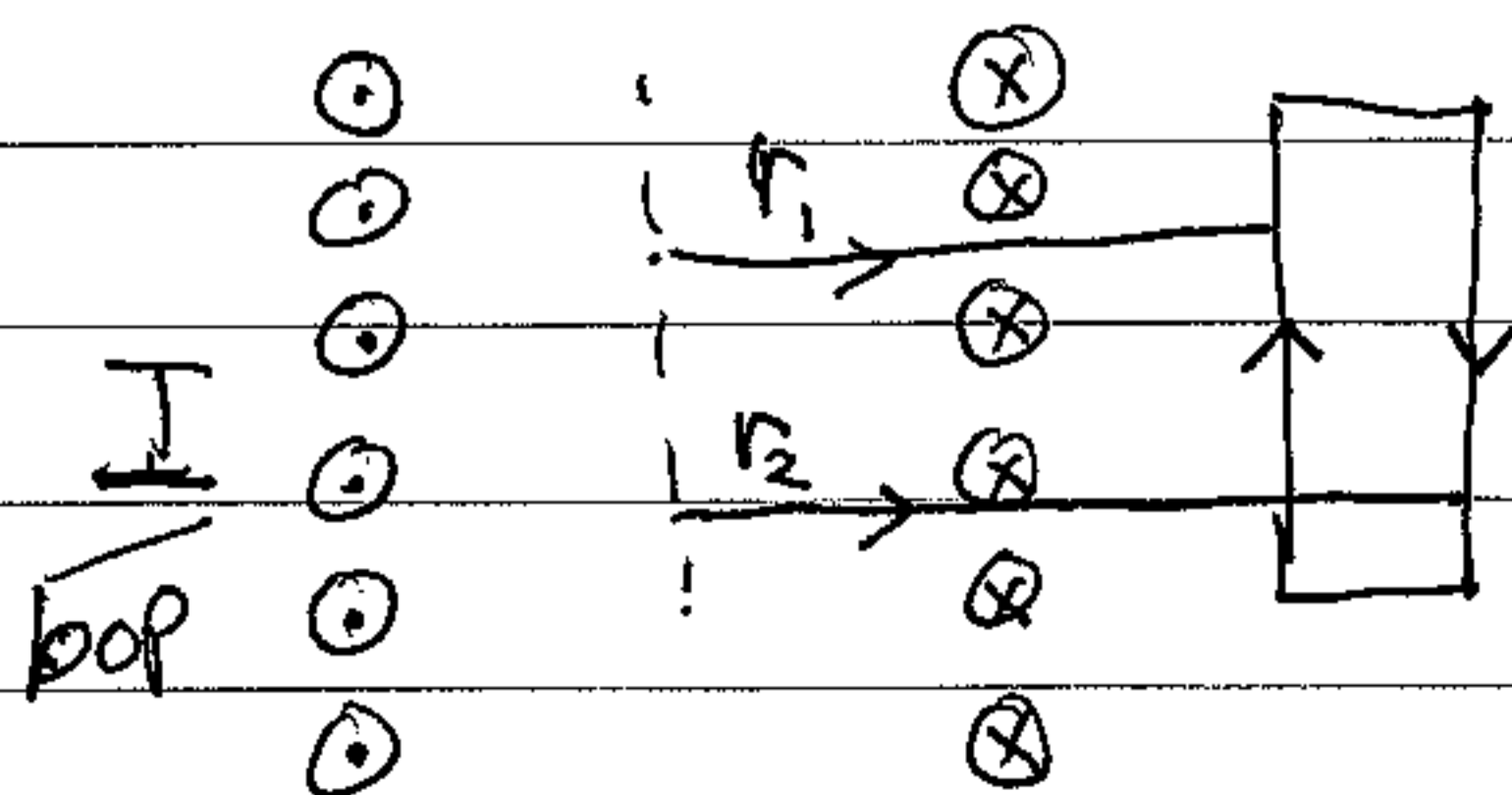
- By symmetry  $B_\phi = 0$ , since current is in  $\hat{\phi}$  direction

$|\vec{B}|$  is independent of  $z$  (infinitely long)  
independent of  $\phi$  (azimuthally symmetric)

Since  $\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow B$  has no  $\hat{r}$  component

$$\Rightarrow \vec{B} = \cancel{B_r \hat{r}} B_z \hat{z}$$

• Outside Solenoid:

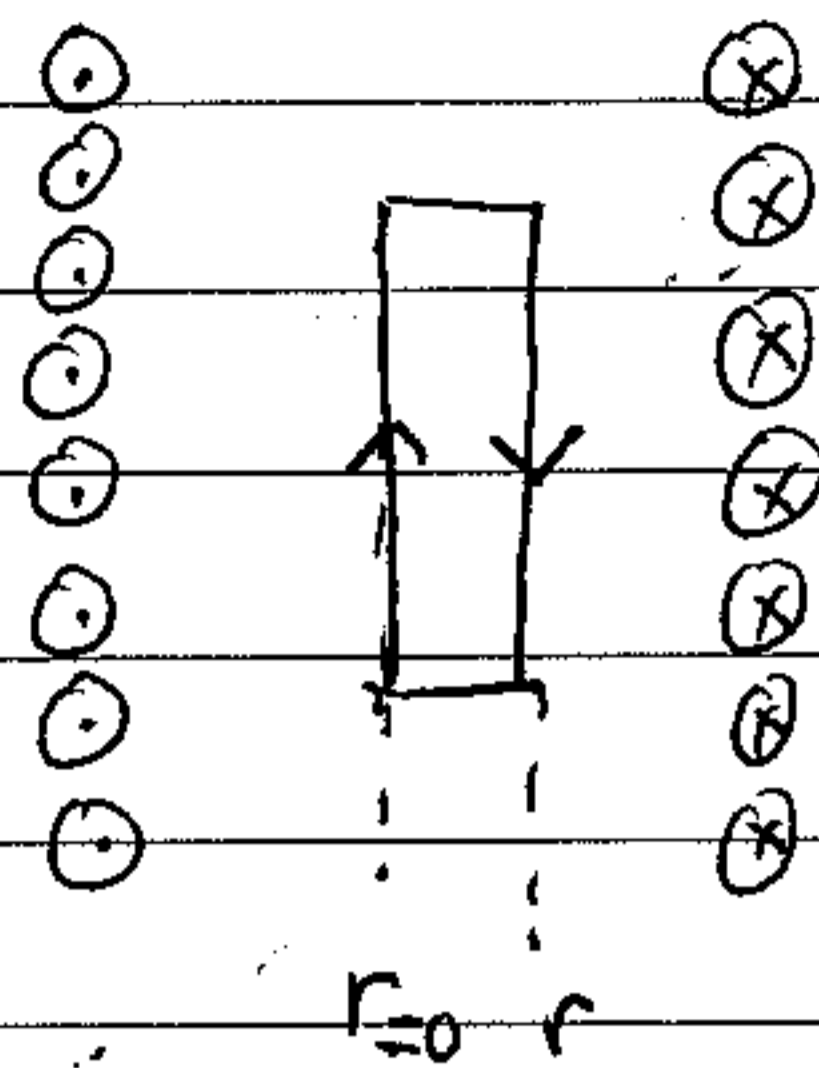


$$\oint_{\text{out}} \vec{B} \cdot d\vec{l} = B_{\text{out}}(r_1) - B_{\text{out}}(r_2) = 0$$

$$\Rightarrow B_{\text{out}}(r_1) = B_{\text{out}}(r_2)$$

But:  $B_{\text{out}} \rightarrow 0$  as  $r \rightarrow \infty$

$$\therefore \boxed{B_{\text{out}} = 0}$$

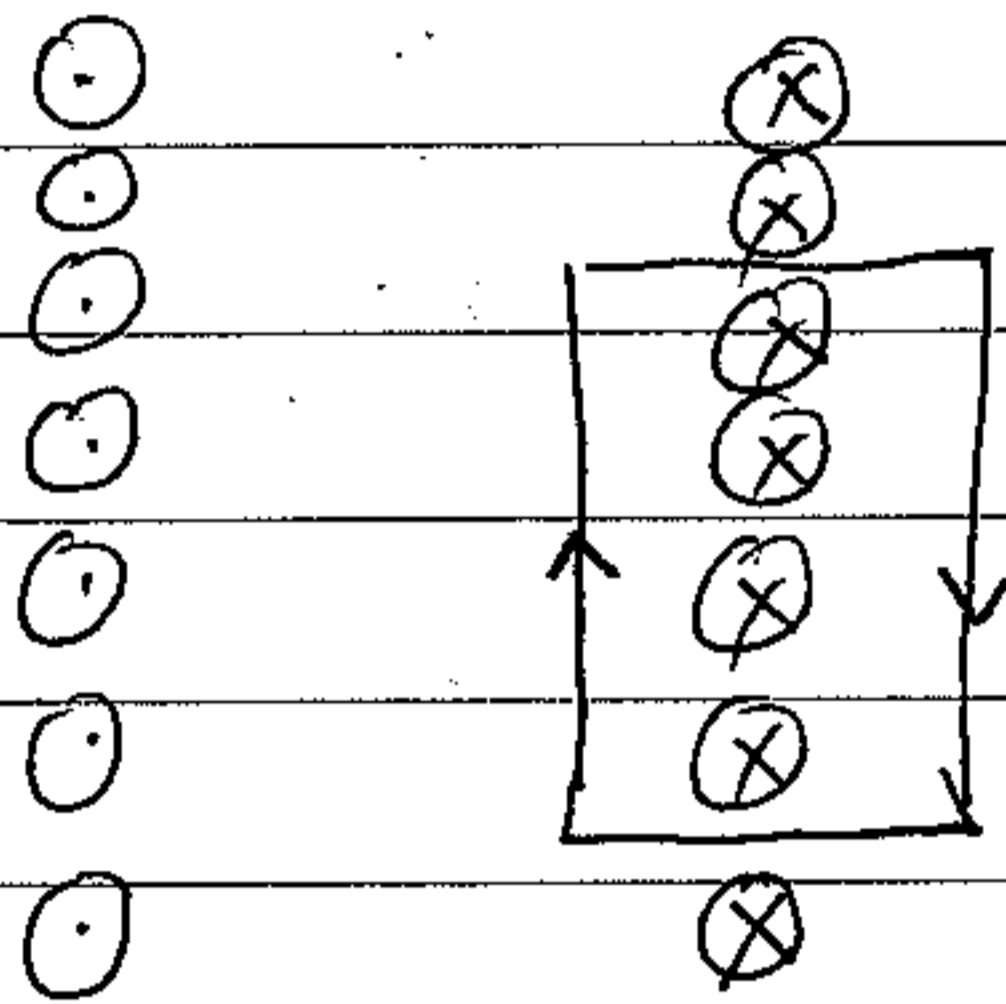


Inside:

$$\oint \vec{B}_m \cdot d\vec{l} = B_m(r_0) - B_m(r) = 0$$

$$\Rightarrow B_m(r) = B_m(r_0)$$

Now consider a loop which straddles inside + outside



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 N I l$$

$$\Rightarrow l(B_{in} - B_{out}) = \mu_0 N I l$$

$$\Rightarrow \vec{B}(r) = \begin{cases} \mu_0 N I \hat{z} & \text{inside} \\ 0 & \text{outside} \end{cases}$$

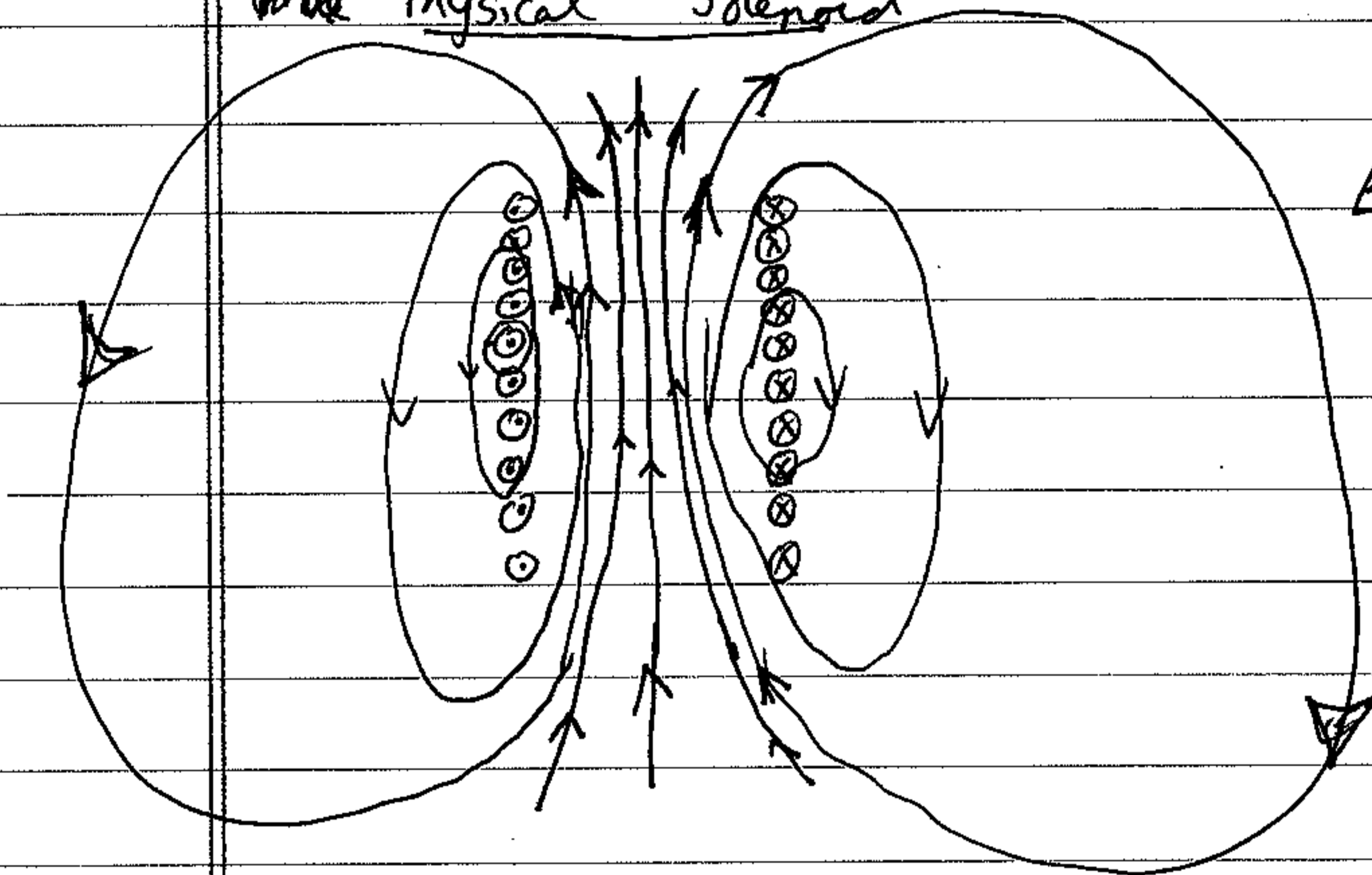
$N = \# \text{ of turns / length}$

## Ideal Solenoid



$\vec{B}$  perfectly uniform inside,  
Zero outside

## Physical Solenoid



Fringing fields

$$|\vec{B}|_{\text{outside}} \ll |\vec{B}|_{\text{inside}}$$

When diameter  $\ll$   
length

~~Parallel plate capacitor~~

as

~~Solenoid~~

Electro-statics

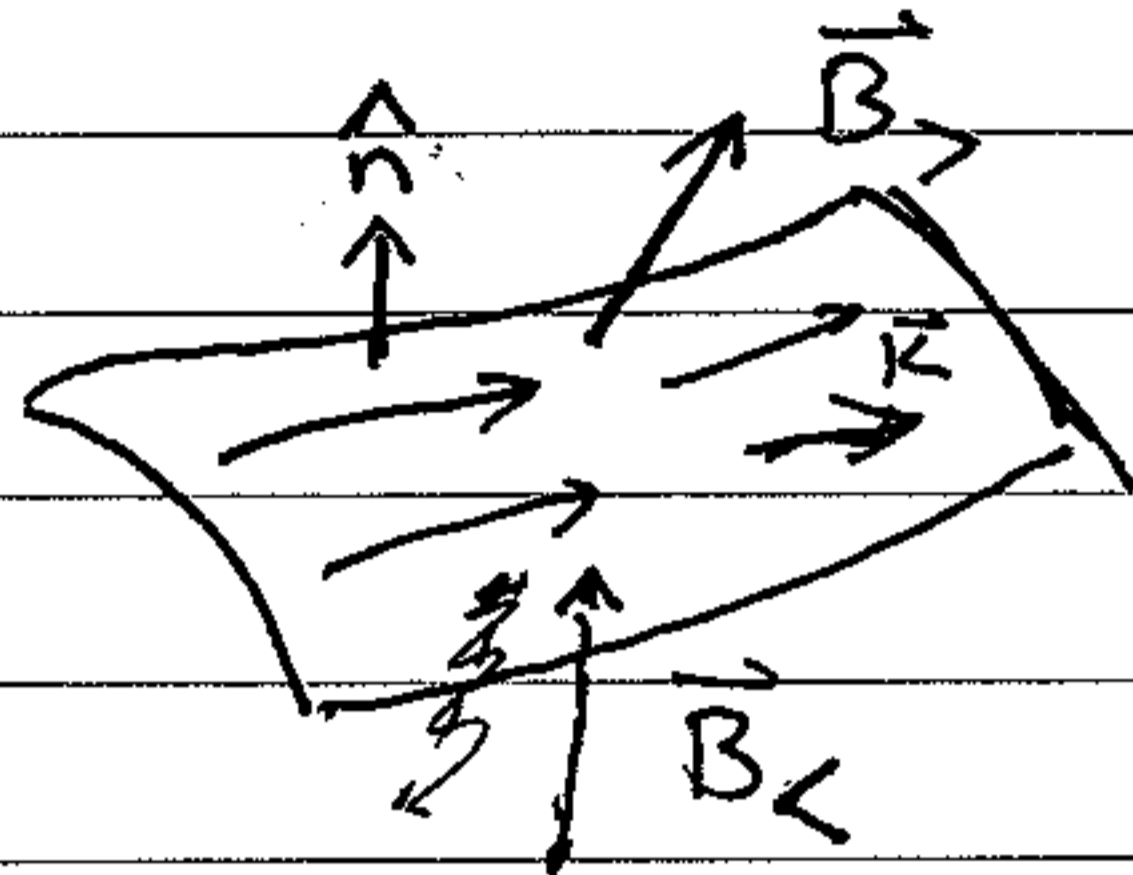
Magneto-statics



## Boundary Conditions on $\vec{B}$ (Magnetostatics)

Fundamental field eqs: 
$$\begin{cases} \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \end{cases}$$

Consider a surface dividing two regions:

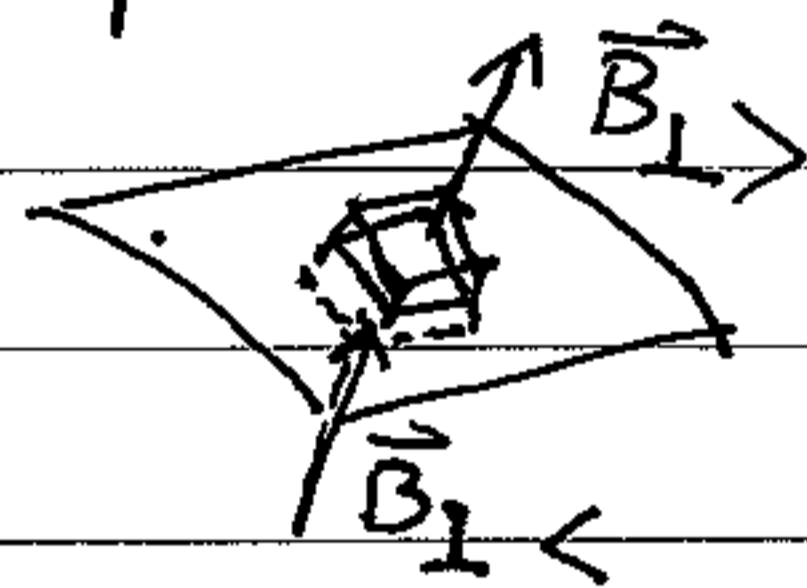


We consider the possibility of current flowing on the surface:  $\vec{K}$  = surface current density

To determine the b.c. on the normal component

$$B_{\perp} \equiv \hat{n} \cdot \vec{B}$$

Take a "pill box" straddling the surface



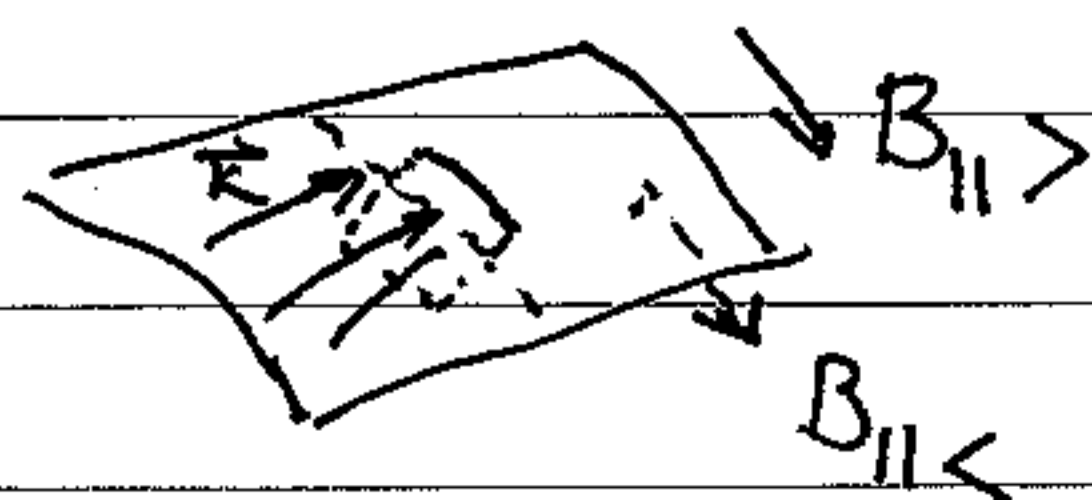
$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \oint \vec{B} \cdot d\vec{a} = 0$$

$$A(B_{\perp} - B_{\perp<}) = 0$$

$$\Rightarrow \boxed{B_{\perp} = B_{\perp<}}$$

To determine the b.c. on the tangential component

Take an Amperian loop straddling the surface



$$\oint \vec{B} \cdot d\vec{l} = l(B_{\parallel} - B_{\parallel<})$$

$$= \mu_0 I_{enc} = \mu_0 K l$$

$$\Rightarrow \boxed{B_{\parallel} - B_{\parallel<} = \mu_0 K}$$