

## Physics 405: Lecture 26

### The Vector Potential

In electrostatics the equation

$$\vec{\nabla} \times \vec{E} = 0 \Rightarrow \boxed{\vec{E} = -\vec{\nabla} V}$$

~~of the potential~~ Where  $V$  is the "electrostatic potential"

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho(\vec{r})}{\epsilon_0} \Rightarrow \boxed{\nabla^2 V = -\frac{\rho(\vec{r})}{\epsilon_0}} \text{ Poisson's Equation}$$

Solutions to electrostatics is thus the solution to Poisson's Eqn. For localized  $\rho(\vec{r})$  with ground @ infinity

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int d^3r' \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

For a ~~given~~ given  $\rho(\vec{r})$  it is generally simpler to find  $V(\vec{r})$  than  $\vec{E}(\vec{r})$  (no vectors to deal with). Moreover, often we are interested in the field away from the charges where  $\rho(\vec{r}) = 0$

$$\Rightarrow \nabla^2 V = 0 \quad (\text{Laplace's Eqn}).$$

Then we have a variety of methods to find the solution using boundary values.

In magneto-statics

$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$ . Thus, in general  $\vec{B} \neq -\vec{\nabla} V_{\text{mag}}$

Magnetic forces are not "conservative".

Magnetic fields do no work.

To see this, look at the Lorentz Force:

$$\vec{F} = q\vec{v} \times \vec{B} = m\vec{a}$$

(point particle, mass  $m$ , charge  $q$ )

~~The~~ The rate at which work is done on a particle

$$\frac{dW}{dt} = \vec{v} \cdot \vec{F} = \vec{v} \cdot (q\vec{v} \times \vec{B}) = 0$$

Said another way, Consider the kinetic energy. The rate at which the kinetic energy changes due to magnetic forces

$$\frac{d}{dt} \left( \frac{1}{2} m v^2 \right) = \frac{1}{2} m \frac{d}{dt} (\vec{v} \cdot \vec{v}) = m \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$= m \vec{a} \cdot \vec{v} = \vec{F} \cdot \vec{v} = 0$$

Magnetic forces can change the direction of  $\vec{v}$ , but not its magnitude

$\vec{B}$ -fields do not work

The magnetic field is, however, mathematically related to a "vector potential"

$$\vec{\nabla} \cdot \vec{B} = 0 \iff \boxed{\vec{B} = \vec{\nabla} \times \vec{A}}$$

It is easy to check  $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$ , but it also follows that if  $\vec{\nabla} \cdot \vec{B} = 0$  then  $\exists \vec{A}(\vec{r})$  s.t.  $\vec{B} = \vec{\nabla} \times \vec{A}$  (Helmholtz theorem).

$$\boxed{\vec{A}(\vec{r}) \equiv \text{Vector Potential}}$$

The vector potential, unlike the scalar potential in electrostatics, is not interpretable in terms of potential energy. It is a calculational tool.

Plugging  $\vec{B} = \vec{\nabla} \times \vec{A}$  into Ampère's Law

$$\vec{\nabla} \times \vec{B} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \mu_0 \vec{J}$$

Aside: Vector identity  $\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}$

$$\Rightarrow \boxed{\vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} = \mu_0 \vec{J}}$$

Yikes!

## "Gauge Invariance"

In electro-statics, the potential is defined up to a constant (the point of "ground")

There is much ~~more~~ more freedom in defining the vector potential for a given  $\vec{J}$ ,

Note: If  $\vec{F} = \vec{\nabla} \chi(\vec{r})$ , for an arbitrary scalar field  $\chi(\vec{r})$   
then  $\vec{\nabla} \times \vec{F} = \vec{\nabla} \times (\vec{\nabla} \chi) = 0$

Thus, we can add to  $\vec{A}(\vec{r})$  an arbitrary vector field  $\vec{\nabla} \chi$ , without changing  $\vec{B}$

$$\vec{A} \Rightarrow \vec{A}' = \vec{A} + \vec{\nabla} \chi : \text{Gauge Transformation}$$

$$\vec{\nabla} \times \vec{A} = \vec{\nabla} \times \vec{A}' = \vec{B} : \text{Physical field}$$

↑                      ↑  
mathematical entity

~~the~~ Said another way: The vector potential  $\vec{A}$  is determined by its curl and its divergence. The curl of  $\vec{A}$  defines the physical magnetic field, but its divergence is arbitrary

Choice of "gauge": In Magnetostatics, we typically choose:

$$\boxed{\vec{\nabla} \cdot \vec{A} = 0}$$

With this choice of gauge.

$$\boxed{\nabla^2 \vec{A} = -\mu_0 \vec{J}}$$

Each Cartesian component of  $\vec{A}$  satisfies a Poisson Eqn, with source determined by the Cartesian component of  $\vec{J}$ .

$$\Rightarrow \boxed{\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3r' \frac{\vec{J}(\vec{r}')}{|\vec{r} - \vec{r}'|}}$$

For a <sup>steady</sup> surface or line current:

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d\vec{\ell} \frac{\vec{K}(\vec{r}')}{|\vec{r} - \vec{r}'|} = \frac{\mu_0 I}{4\pi} \int d\vec{\ell} \frac{1}{|\vec{r} - \vec{r}'|}$$

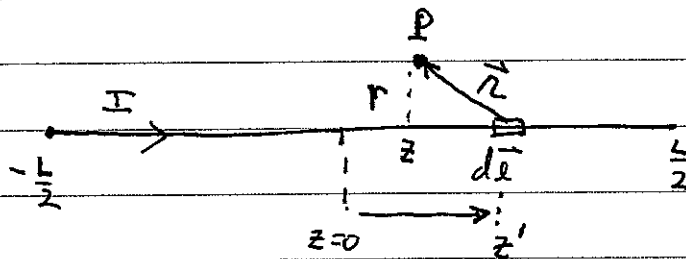
In contrast to the electrostatic scalar potential, the magnetostatic vector potential is not as useful a calculational tool because the argument of the integral is still a vector. In electrodynamics as we will see in 406, the vector potential is central. More often, in practical calculations of  $\vec{B}$ , we want to find the field in a region where  $\vec{J} = 0$

$\Rightarrow$  if ~~the~~ @ point of observation  $\vec{J} = 0$

$$\vec{\nabla} \times \vec{B} = 0 \Rightarrow \vec{B} = -\vec{\nabla} U_m \leftarrow \begin{array}{l} \text{magnetic} \\ \text{"pseudo"} \\ \text{potential"} \end{array}$$

One must be careful about connecting different <sup>"simply connected"</sup> regions, but very useful practically.

## Example: Vector Potential of a Line Charge



$$\vec{A}(r, z) = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}}{R} = \frac{\mu_0 I}{4\pi} \hat{z} \int_{-L/2}^{L/2} \frac{dz'}{\sqrt{r^2 + (z-z')^2}}$$

$$\Rightarrow \vec{A}(r, z) = \frac{\mu_0 I}{4\pi} \hat{z} \ln \left[ \frac{L + 2z + \sqrt{L^2 - 4Lz + 4(r^2 + z^2)}}{-L + 2z + \sqrt{L^2 + 4Lz + 4(r^2 + z^2)}} \right]$$

Not too pretty

Using Curl in Cylindrical coords

$$\vec{B}(r, z) = \nabla \times \vec{A} = -\frac{\partial A_z}{\partial r} \hat{\phi} = \underline{A \text{ mess!}}$$

limit of an infinite wire: set  $z=0$ ,

$$\vec{A}(r, z=0) = \frac{\mu_0 I}{4\pi} \hat{z} \ln \left[ \frac{L + \sqrt{L^2 + 4r^2}}{-L + \sqrt{L^2 + 4r^2}} \right]$$

$$\lim_{L \rightarrow \infty} \vec{A}(r, z=0) = \frac{\mu_0 I}{4\pi} \hat{z} \ln \left[ \frac{2}{-1 + (1 + \frac{4r^2}{L^2})^{1/2}} \right] \approx \frac{\mu_0 I}{4\pi} \hat{z} \ln \left[ \frac{L^2}{r^2} \right]$$

limit  
 $L \rightarrow \infty$

$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0 I}{2\pi r} \hat{z}$$

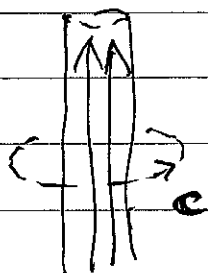
As expected

## Vector Potential of a Solenoid

Consider infinite solenoid with  $N$  turns/length.  
Instead of finding  $\vec{A}$  from current, we can find it from  $\vec{B}$  by integration:

Note: 
$$\int_S \vec{B} \cdot d\vec{a} = \int_S (\nabla \times \vec{A}) \cdot d\vec{a} = \oint_C \vec{A} \cdot d\vec{l}$$

The contour integral of  $\vec{A}$  around a closed loop is the flux of  $\vec{B}$  through the loop



$\Rightarrow$  Use reasoning of Ampère's Law

$$\nabla \times \vec{A} = \vec{B}$$

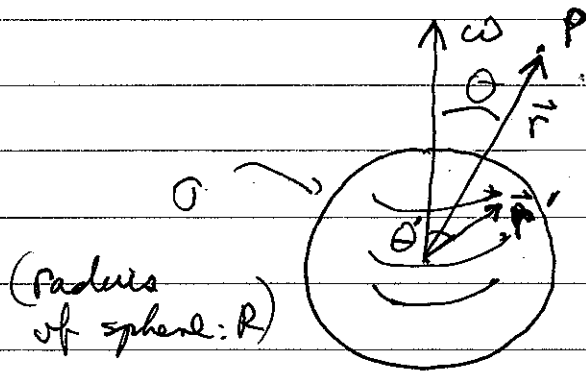
$\Rightarrow \vec{B}$  uniform in  $z$ -direction with  $\nabla \cdot \vec{A} = 0$

$\vec{A}$  in  $\hat{\phi}$ -direction, varying w/  $r$

$$\Rightarrow 2\pi r A(r) = \begin{cases} B(\pi r^2) & r < R \\ B(\pi R^2) & r > R \end{cases}$$

$$\Rightarrow \vec{A}(r) = B r \hat{\phi} = \begin{cases} \hat{\phi} \frac{\mu_0 N I}{2} r & r < R \\ \hat{\phi} \frac{\mu_0 N I}{2} \frac{R^2}{r} & r > R \end{cases}$$

Example: Spherical shell of charge rotating at angular velocity  $\omega$



Surface charge density

$$\vec{K}(\theta) = \sigma \vec{v}(\theta)$$

$$\vec{v}(\theta) = \vec{\omega} \times \vec{r}'$$

$$= \omega R \sin \theta' \hat{\phi}$$

Note: Since  $|\vec{K}|$  varies with  $\theta'$  and points in  $\hat{\phi}$  direction, so simple symmetry to use Ampère's law

Find vector ~~scalar~~ potential @ point of observation  $P$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{K}(\vec{r}') da'}{|\vec{r} - \vec{r}'|}$$

$$da' = R^2 \sin \theta' d\theta' d\phi'$$

~~$$= 2\pi R^2 \sin \theta' d\theta'$$~~

azimuthal symmetry

Note:  $\hat{\phi} = -\sin \phi' \hat{x} + \cos \phi' \hat{y}$  (depends on  $\phi'$ )

$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_0 \sigma R^3 \omega}{4\pi} \int \frac{\sin^2 \theta' d\theta' (-\sin \phi' \hat{x} + \cos \phi' \hat{y}) d\phi'}{\sqrt{r^2 + R^2 - 2(rR) \hat{r} \cdot \hat{r}'}}$$

Yick!  $\nabla$



Transforming coordinates, so that  $\hat{z}$  along symmetry axis, Griffiths was able to solve this integral (see Text, example Ex: 11)

Solution:

$$\vec{A}(\vec{r}) = \begin{cases} \frac{\mu_0 R \omega \sigma}{3} r \sin \theta \hat{\phi} & r < R \\ \frac{\mu_0 R^4 \omega \sigma}{3} \frac{\sin \theta}{r^2} \hat{\phi} & r > R \end{cases}$$

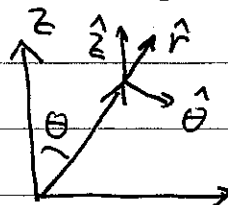
Curl in spherical

$$\vec{B} = \nabla \times \vec{A} = \hat{r} \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta A_\phi) - \frac{\partial A_\theta}{\partial \phi} \right] + \hat{\theta} \left[ \frac{1}{r \sin \theta} \frac{\partial A_r}{\partial \phi} - \frac{1}{r} \frac{\partial}{\partial r} (r A_\phi) \right] + \hat{\phi} \frac{1}{r} \left[ \frac{\partial}{\partial r} (r A_\theta) - \frac{\partial A_r}{\partial \theta} \right]$$

Here  $\vec{A} = A(r, \theta) \hat{\phi} \Rightarrow \vec{B} = \hat{r} \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\phi) - \hat{\theta} \frac{1}{r} \frac{\partial}{\partial r} (r A_\phi)$

$\Rightarrow r \leq R$   
Inside

$$\vec{B}(r, \theta) = \frac{2\mu_0 R \omega \sigma}{3} (\cos \theta \hat{r} - \sin \theta \hat{\theta})$$



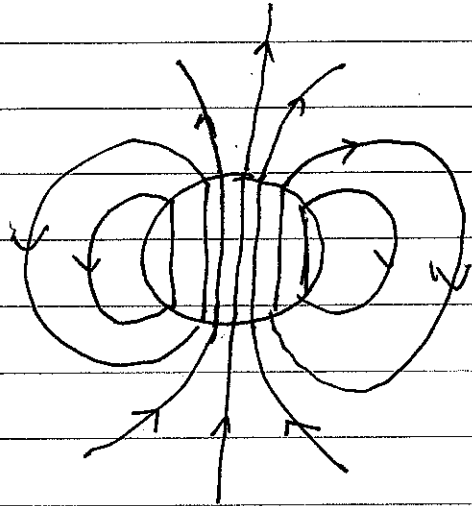
$\Rightarrow r \leq R$

$$\vec{B}(r, \theta) = \frac{2\mu_0 R \omega \sigma}{3} \hat{z} = \frac{2\mu_0 R \omega \sigma}{3} \vec{\omega} \text{ uniform}$$

Outside  
 $r \geq R$

$$\vec{B}(r, \theta) = \frac{\mu_0 R^4 \omega \sigma}{3r^3} (2 \cos \theta \hat{r} - \sin \theta \hat{\theta})$$

= Dipole Field  $\sim \frac{1}{r^3}$



Spinning sphere of charge

$\implies$  Perfect magnetic dipole