

Problem #1

Maxwell's equations for electro/magneto statics
with magnetic monopoles

$$\vec{\nabla} \cdot \vec{E} = \rho_E / \epsilon_0 \quad \vec{\nabla} \times \vec{E} = \frac{\vec{J}_M}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = \mu_0 \rho_M \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_E$$

(a) Show that solution is

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int dV' \rho_E(\vec{r}') \frac{\hat{r}}{r^2} + \frac{1}{4\pi\epsilon_0} \int dV' \frac{\vec{J}_M(\vec{r}') \times \hat{r}}{r^2}$$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int dV' \rho_M(\vec{r}') \frac{\hat{r}}{r^2} + \frac{\mu_0}{4\pi} \int dV' \frac{\vec{J}_E(\vec{r}') \times \hat{r}}{r^2}$$

We must take 4 derivatives:

$$\vec{\nabla} \cdot \int dV' \rho(\vec{r}') \frac{\hat{r}}{r^2}, \quad \vec{\nabla} \cdot \int dV' \vec{J}(\vec{r}') \times \frac{\hat{r}}{r^2}$$

$$\vec{\nabla} \times \int dV' \rho(\vec{r}') \frac{\hat{r}}{r^2}, \quad \vec{\nabla} \times \int dV' \vec{J}(\vec{r}') \times \frac{\hat{r}}{r^2}$$

where $\rho = \rho_E$ or ρ_M , $\vec{J} = \vec{J}_E$ or \vec{J}_M

and $\vec{\nabla}$ is the "del operator" with respect to "unprimed" coordinates. Also, $\vec{r} = \vec{r} - \vec{r}'$

$$(1) \vec{\nabla} \cdot \int dV' \rho(\vec{r}') \frac{\hat{r}}{r^2} = \int dV' \vec{\nabla} \cdot \left(\rho(\vec{r}') \frac{\hat{r}}{r^2} \right)$$

$$= \int dV' \rho(\vec{r}') \vec{\nabla} \cdot \frac{\hat{r}}{r^2} \quad (\text{since } \vec{\nabla} \text{ acts only on "unprimed variables"})$$

$$\text{Now } \frac{\hat{r}}{r^2} = -\vec{\nabla} \frac{1}{r} \Rightarrow \vec{\nabla} \cdot \frac{\hat{r}}{r^2} = -\nabla^2 \frac{1}{r} = 4\pi \delta^{(3)}(\vec{r}) = 4\pi \delta^{(3)}(\vec{r} - \vec{r}')$$

$$\therefore \vec{\nabla} \cdot \int dV' \rho(\vec{r}') \frac{\hat{r}}{r^2} = 4\pi \int dV' \rho(\vec{r}') \delta^{(3)}(\vec{r} - \vec{r}') = 4\pi \rho(\vec{r})$$

Problem 2

(a) If \vec{B} is uniform show that $\vec{\nabla} \times \vec{A} = \vec{B}$, $\vec{\nabla} \cdot \vec{A} = 0$
if we chose $\vec{A} = \frac{-\vec{r} \times \vec{B}}{2}$

Use the "product rules" on the inside cover of Griffiths

$$\vec{\nabla} \cdot \vec{A} = -\frac{1}{2} \vec{\nabla} \cdot (\vec{r} \times \vec{B}) = -\frac{\vec{B}}{2} \cdot (\vec{\nabla} \times \vec{r}) + \frac{\vec{r}}{2} \cdot (\vec{\nabla} \times \vec{B}) \quad (\vec{B} \text{ uniform})$$

$$\vec{\nabla} \times \vec{r} = 0 \quad \text{proof: } \vec{\nabla} \times \vec{r} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = 0$$

$$\Rightarrow \vec{\nabla} \cdot \vec{A} = 0 \quad \checkmark$$

$$\vec{\nabla} \times \vec{A} = -\frac{1}{2} \vec{\nabla} \times (\vec{r} \times \vec{B}) = -\frac{1}{2} \left\{ (\vec{B} \cdot \vec{\nabla}) \vec{r} - (\vec{r} \cdot \vec{\nabla}) \vec{B} + \vec{r} (\vec{\nabla} \cdot \vec{B}) - \vec{B} (\vec{\nabla} \cdot \vec{r}) \right\}$$

Now $\vec{\nabla} \cdot \vec{B} = 0$ and $(\vec{r} \cdot \vec{\nabla}) \vec{B} = 0$ (since \vec{B} is uniform)

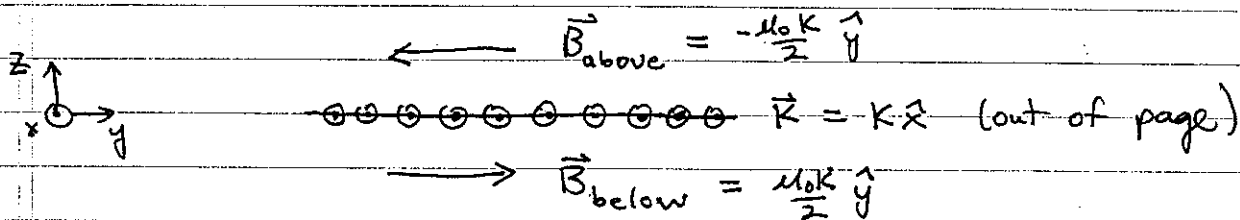
$$\Rightarrow \vec{\nabla} \times \vec{A} = -\frac{1}{2} \left\{ (\vec{B} \cdot \vec{\nabla}) \vec{r} - \vec{B} (\vec{\nabla} \cdot \vec{r}) \right\}$$

Aside $(\vec{B} \cdot \vec{\nabla}) \vec{r} = (B_x \frac{\partial}{\partial x} + B_y \frac{\partial}{\partial y} + B_z \frac{\partial}{\partial z})(x \hat{x} + y \hat{y} + z \hat{z})$
 $= B_x \hat{x} + B_y \hat{y} + B_z \hat{z} = \vec{B}$

$$\vec{\nabla} \cdot \vec{r} = \frac{\partial}{\partial x} x + \frac{\partial}{\partial y} y + \frac{\partial}{\partial z} z = 3$$

$$\Rightarrow \vec{\nabla} \times \vec{A} = -\frac{1}{2} \left\{ \vec{B} - 3\vec{B} \right\} = \vec{B} \quad \checkmark$$

(b) For the uniform sheet of current we found



$$\Rightarrow \vec{A}_{\text{above}} = -\frac{1}{2} (\vec{r} \times \vec{B}_{\text{above}}) = -\frac{1}{2} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ x & y & z \\ 0 & -\frac{\mu_0 K}{2} & 0 \end{vmatrix}$$

$$\Rightarrow \vec{A}_{\text{above}} = +\frac{\mu_0 K}{4} (x \hat{z} - z \hat{x})$$

Similarly $\vec{A}_{\text{below}} = -\frac{1}{2} (\vec{r} \times \vec{B}_{\text{below}}) = -\vec{A}_{\text{above}} = -\frac{\mu_0 K}{4} (x \hat{z} - z \hat{x})$

$$\Rightarrow \boxed{\vec{A} = \text{sign}(z) \frac{\mu_0 K}{4} (x \hat{z} - z \hat{x})}$$

This form of the vector potential, though correct, is strange. Note that \vec{A} depends on the x -coordinate of observation. But the current sheet is infinite in x , so how can we know where $x=0$ is! Of course \vec{B} is independent of x , so all is OK. Another choice for \vec{A} which doesn't have this unphysical character is

$$\vec{A}' = -\text{sign}(z) \frac{\mu_0 K}{2} z \hat{x}$$

Then you can easily convince yourself that

$$\vec{\nabla} \cdot \vec{A}' = 0 \quad \text{and} \quad \vec{\nabla} \times \vec{A}' = \vec{B}$$

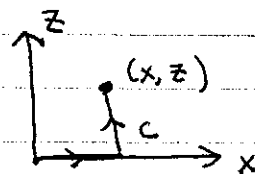
The two choices of \vec{A} must be related by a gauge transformation. Let's see this explicitly for $z > 0$

~~$\vec{A}' = \vec{A} + \vec{\nabla}\chi$~~ for some scalar χ . Find χ

$$\vec{A}' - \vec{A} = -\frac{\mu_0 K}{2} z \hat{x} - \frac{\mu_0 K}{4} (x \hat{z} - z \hat{x})$$

$$= -\frac{\mu_0 K}{4} (x \hat{z} + z \hat{x}) = -\vec{\nabla}\chi = \frac{\partial\chi}{\partial x} \hat{x} + \frac{\partial\chi}{\partial y} \hat{y} + \frac{\partial\chi}{\partial z} \hat{z}$$

Integrating along the contour



we find

$$\chi = -\frac{\mu_0 K}{4} xz \Rightarrow \vec{\nabla}\chi = -\frac{\mu_0 K}{4} (x \hat{z} + z \hat{x}) \checkmark$$

Moral of the story

Even by restricting $\vec{\nabla} \cdot \vec{A} = 0$, there are still an infinite number of vector potentials which generate the same magnetic field \vec{B} , which are related by a gauge transformation

$$\vec{A}' = \vec{A} + \vec{\nabla}\chi$$

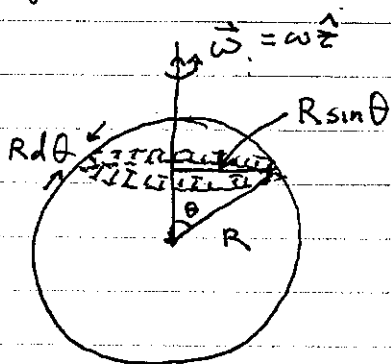
$$\vec{\nabla} \cdot \vec{A} = \vec{\nabla} \cdot \vec{A}' = 0 \quad \text{if} \quad \nabla^2 \chi = 0$$

Problem 3: Sphere with uniform surface charge σ rotating with ~~angh~~ angular frequency ω

From P.S. #10, we found the surface current

$$\vec{K}(\theta) = \sigma \omega R \sin \theta \hat{\phi}$$

(a) Breaking up the surface into current rings



The ring at (R, θ) has

- Radius of ring = $R \sin \theta$

- differential current in ring

$$dI(\theta) = K R d\theta = \sigma \omega R^2 \sin \theta d\theta$$

The magnetic dipole moment associated with this differential ring of current is

$$\begin{aligned} d\vec{m} &= dI(\theta) (\text{Area of ring}) \hat{z} = dI(\theta) \pi (R \sin \theta)^2 \hat{z} \\ &= \pi \sigma \omega R^4 \sin^3 \theta \hat{z} d\theta \end{aligned}$$

Thus the total magnetic dipole moment is

$$\begin{aligned} \vec{m} &= \int d\vec{m} = \int_0^\pi d\theta \pi \sigma \omega R^4 \sin^3 \theta \hat{z} \\ &= \pi \sigma \omega R^4 \int_0^\pi d\theta (1 - \cos^2 \theta) \sin \theta d\theta \hat{z} \\ &= \pi \sigma \omega R^4 \left[-\cos \theta + \frac{\cos^3 \theta}{3} \right]_0^\pi \hat{z} \\ &= \pi \sigma \omega R^4 \left[+1 - \frac{1}{3} + 1 - \frac{1}{3} \right] \hat{z} \end{aligned}$$

$$\Rightarrow \boxed{\vec{m} = \frac{4\pi R^3}{3} (\sigma \omega R) \hat{z}}$$

As in problem set #10

(b) The vector potential at point \vec{r} with $|\vec{r}| \gg R$ is

$$\vec{A} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2} = \frac{\mu_0}{4\pi} \frac{m \sin \theta}{r^2} \hat{\phi}$$

and the magnetic field is

$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0}{4\pi} \left(\frac{2m \cos \theta}{r^3} \hat{r} + \frac{m \sin \theta}{r^3} \hat{\theta} \right)$$

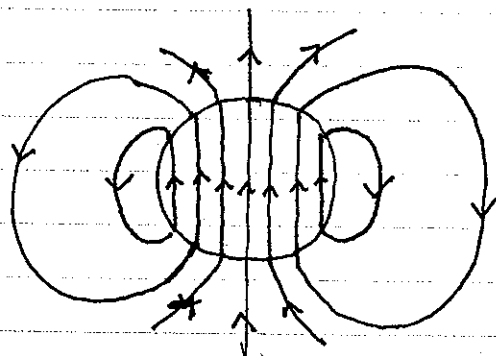
$$\Rightarrow \boxed{\vec{B} = \frac{\mu_0 \sigma \omega R^4}{3} \frac{1}{r^3} (2 \cos \theta \hat{r} + \sin \theta \hat{\theta})}$$

Note at $\theta=0$ $r=z$ $\hat{r} = \hat{z}$

$$\Rightarrow \text{On axis: } \vec{B}(z) = \frac{2 \mu_0 \sigma \omega R^4}{3 z^3} \hat{z}$$

This is the answer we found in P.S. #10 using the Biot-Savart law for any $z \geq R$.

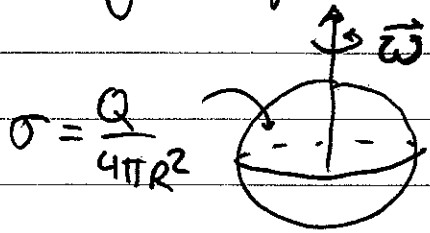
The answer boxed above is exact for any $r > R$. The magnetic field associated with a rotating sphere of charge is a pure dipole field outside the sphere. Inside the field is uniform $\vec{B}_{\text{inside}} = \frac{2}{3} \mu_0 \sigma \omega R \hat{z}$



Note $\nabla \cdot \vec{B} = 0$

The discontinuity in of the tangential component of \vec{B} follows from the boundary conditions

(c) Gyro-magnetic ratio



Spinning ball, mass M

$$\vec{L} = I_{\text{ball}} \vec{\omega}$$

moment of inertia (spherical shell)

Mass on shell, $I_{\text{ball}} = \frac{2}{3} MR^2$

$$\Rightarrow \vec{L} = \frac{2}{3} MR^2 \vec{\omega}$$

Magnetic moment: $\vec{m} = \frac{4\pi R^3}{3} \left(\frac{Q}{4\pi R^2} \omega R \right) \hat{z}$

$$\vec{m} = \frac{\pi R^2}{3} Q \vec{\omega}$$

$$\Rightarrow \frac{|\vec{m}|}{|\vec{L}|} = \frac{Q}{2M}$$

$$\frac{|\vec{m}|}{|\vec{L}|} = \frac{Q}{2M}$$

Gyromagnetic ratio