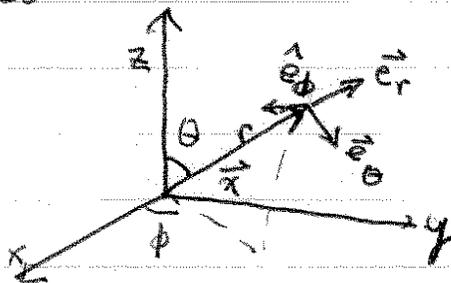


Lecture 8 : Central Potentials and the Radial Equation

Review Classical Dynamics

A central force is one that depends only on the distance from the origin. In such cases it is most convenient to use spherical coordinates to describe dynamics

$$\int d^3x = \int_0^\infty r^2 dr \int d\Omega$$



Note: $\vec{e}_r, \vec{e}_\theta, \vec{e}_\phi$ depend on the position \vec{x}

$$\vec{e}_r = \frac{\vec{x}}{r}$$

Since for a central force \vec{F} is in the \vec{e}_r direction, the potential energy must be a function only on r and not θ and ϕ $V(x, y, z) = V(r)$

\Rightarrow Hamiltonian for a spinless particle

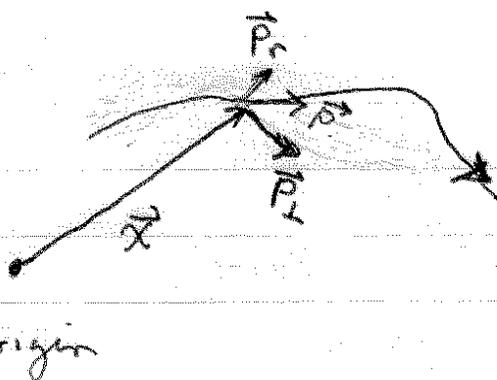
$$H = \frac{p^2}{2m} + V(r)$$

Classical equations of motion

$$\dot{\vec{x}} = \frac{\vec{p}}{m}$$

$$\dot{\vec{p}} = -\vec{\nabla}V = -\frac{dV}{dr} \vec{e}_r$$

It is useful to break up the trajectory into radial and angular motion



$$\vec{p} = \vec{p}_r + \vec{p}_\perp$$

radial momentum

$$p_r = |\vec{p}_r| = \vec{e}_r \cdot \vec{p}$$

$$= \frac{\vec{x}}{r} \cdot \vec{p}$$

The angular momentum $\vec{L} = \vec{x} \times \vec{p} = \vec{x} \times (\vec{p}_r + \vec{p}_\perp)$

$$\Rightarrow \vec{L} = \vec{x} \times \vec{p}_\perp \quad \Rightarrow \quad \frac{d\vec{L}}{dt} = \underbrace{\dot{\vec{x}} \times \vec{p}_\perp}_{\parallel \vec{p}} + \underbrace{\vec{x} \times \dot{\vec{p}}_\perp}_0$$

$\Rightarrow \boxed{\frac{d\vec{L}}{dt} = 0}$ In a central potential angular momentum is conserved

Decomposition of kinetic energy into radial and angular components:

Note: $|\vec{L}|^2 = L^2 = |\vec{x} \times \vec{p}_\perp|^2 = r^2 p_\perp^2 \Rightarrow p_\perp^2 = \frac{L^2}{r^2}$

$$\therefore |\vec{p}|^2 = p^2 = p_r^2 + p_\perp^2 = p_r^2 + \frac{L^2}{r^2}$$

$$\therefore H = \frac{p_r^2}{2m} + \frac{L^2}{2mr^2} + V(r)$$

Since L is fixed for a given trajectory we can set it equal to a constant

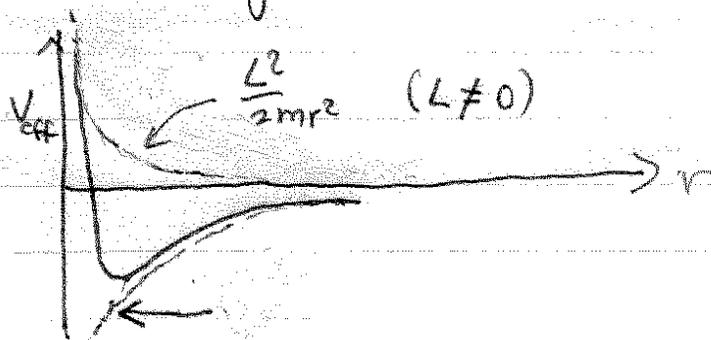
$$\Rightarrow H = \frac{p_r^2}{2m} + V_{\text{eff}}^{(L)}(r)$$

$$V_{\text{eff}}^{(L)}(r) = \left(\frac{L^2}{2mr^2} \right) + V(r)$$

Angular momentum "barrier"

For a fixed L the dynamics is reduced to one dimension

e.g. $V(r) = \frac{C}{r}$
 $C > 0$



Note

$$0 \leq r < \infty$$

no negative r

The angular momentum term provides a "centrifugal" barrier to motion near origin



Quantum problem:

$$\hat{H} = \frac{\hat{p}^2}{2m} + V(\hat{r}) \quad , \quad \hat{r}^2 = \hat{x}^2 + \hat{y}^2 + \hat{z}^2$$

Angular momentum $\hat{L} = \hat{x} \times \hat{p}$

$$\left. \begin{aligned} \text{Aside: } [\hat{L}_i, \hat{p}_j] &= i\hbar \epsilon_{ijk} \hat{p}_k \\ [\hat{L}_i, \hat{x}_j] &= i\hbar \epsilon_{ijk} \hat{x}_k \end{aligned} \right\} \text{Vector operators}$$

$$\Rightarrow [\hat{L}_i, \hat{p}^2] = [\hat{L}_i, \hat{r}^2] = 0$$

\hat{p}^2 and \hat{r}^2 are scalar w.r.t. rotation

\therefore If \hat{V} is a function only of \hat{r}

$$\begin{aligned} [\hat{H}, \hat{L}_i] &= 0 \quad \text{i.e. } \hat{H} \text{ is rotationally} \\ \Rightarrow [\hat{H}, \hat{L}^2] &= 0 \quad \text{invariant about any axis} \end{aligned}$$

$\Rightarrow L$ is conserved

Separability of \hat{H}

Aside: $\hat{L}^2 = \hat{L} \cdot \hat{L} = (\hat{x} \times \hat{p}) \cdot (\hat{x} \times \hat{p}) = -(\hat{x} \times \hat{p}) \cdot (\hat{p} \times \hat{x})$
 $= -\hat{x} \cdot [\hat{p} \times (\hat{p} \times \hat{x})] = -\hat{x} \cdot [\hat{p}(\hat{p} \cdot \hat{x}) - \hat{p}^2 \hat{x}]$

$$\Rightarrow \hat{L}^2 = -(\hat{x} \cdot \hat{p})(\hat{p} \cdot \hat{x}) + \hat{x} \cdot (\hat{p}^2 \hat{x})$$

Aside: $\hat{p}^2 \hat{x} = \hat{x} \hat{p}^2 - 2i\hbar \hat{p}$

$$\Rightarrow \hat{L}^2 = \hat{p}^2 \hat{p}^2 - (\hat{x} \cdot \hat{p})(\hat{p} \cdot \hat{x}) - 2i\hbar \hat{x} \cdot \hat{p}$$

$$\Rightarrow \hat{p}^2 = \left\{ \frac{1}{r^2} (\hat{x} \cdot \hat{p})(\hat{p} \cdot \hat{x}) + \frac{2i\hbar}{r^2} \hat{x} \cdot \hat{p} \right\} + \frac{\hat{L}^2}{r^2}$$

Classically $p^2 = p_r^2 + \frac{L^2}{r^2}$

$$\Rightarrow \boxed{\hat{p}^2 = \hat{p}_r^2 + \frac{\hat{L}^2}{r^2}}$$

$\hat{p}_r^2 = \frac{1}{r^2} (\hat{x} \cdot \hat{p})(\hat{p} \cdot \hat{x}) + \frac{2i\hbar}{r^2} \hat{x} \cdot \hat{p}$ Careful at origin

Does this make sense?

Classically $p_r = \vec{e}_r \cdot \vec{p} = \frac{\vec{x}}{r} \cdot \vec{p}$

Quantum $\hat{p}_r = \frac{1}{2} \left(\frac{\hat{x}}{r} \cdot \hat{p} + \hat{p} \cdot \frac{\hat{x}}{r} \right)$

Check \hat{p}_r^2 gives result above

Thus,
$$\hat{H} = \frac{\hat{p}_r^2}{2m} + \frac{\hat{L}^2}{2m\hat{r}^2} + V(\hat{r})$$

3 degrees of freedom requires three mutually commuting operators to specify state

$$\begin{aligned} [\hat{H}, \hat{L}^2] &= 0 & \text{and} & \quad [\hat{H}, \hat{L}_i] = 0 \\ [\hat{L}^2, \hat{L}_i] &= 0 & \text{but} & \quad [\hat{L}_i, \hat{L}_j] \neq 0 \end{aligned}$$

⇒ Pick one component of \hat{L} (say z)

⇒ Mutually commuting set $\{\hat{H}, \hat{L}^2, \hat{L}_z\}$

Decompose Hilbert space as tensor product in spherical coordinates:

$$\mathcal{H} = h_r \otimes h_\theta \otimes h_\phi$$

~~Energy~~ Energy eigenstates:

$$|\psi_{n_r, l, m}\rangle = |n_r\rangle \otimes |l, m\rangle$$

radial state acts on h_r
eigenstates of \hat{L}^2 and \hat{L}_z acts on $h_\theta \otimes h_\phi$

$$\hat{H} |\psi_{n_r, l, m}\rangle = E_{n_r, l} |\psi_{n_r, l, m}\rangle$$

Note: \hat{H} independent of $\hat{L}_z \Rightarrow E$ independent of $m \Rightarrow$ essential degeneracy

$$\hat{H} |\psi_{n_r, l, m}\rangle = \left(\frac{\hat{p}_r^2}{2m} + \frac{\hbar^2}{2mr^2} l(l+1) + V(\hat{r}) \right) |n_r\rangle \otimes |l, m\rangle$$

$$= E_{n_r, l} |n_r\rangle \otimes |l, m\rangle$$

Project out $|l, m\rangle$ component

radial equation:

$$\Rightarrow \left[\frac{\hat{p}_r^2}{2m} + \frac{\hbar^2}{2mr^2} l(l+1) + V(\hat{r}) \right] |n_r\rangle = E_{n_r, l} |n_r\rangle$$

$V_{\text{eff}}^{(l)}(\hat{r})$

Position representation:

$$\psi(\vec{x}) = \psi(r, \theta, \phi) = \langle \vec{x} | \psi \rangle$$

$$\langle \psi | \psi \rangle = \int_0^\infty r^2 dr \int d\Omega |\psi(r, \theta, \phi)|^2$$

Eigenstates for central potential:

$$\psi_{n_r, l, m}(r, \theta, \phi) = \langle r | n_r \rangle \langle \theta, \phi | l, m \rangle$$

$$\equiv R_{n_r}(r) Y_{l, m}(\theta, \phi)$$

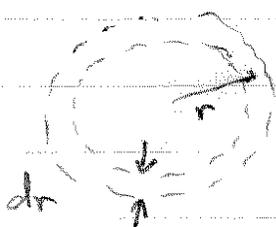
\uparrow
radial wave function

$$\langle \psi | \psi \rangle = \int_0^\infty r^2 |R_{n_r}(r)|^2 dr \underbrace{\int d\Omega |Y_{l, m}(\theta, \phi)|^2}_{=1}$$

Normalization of radial wave function

$$\int_0^{\infty} r^2 |R_{n_r}(r)|^2 dr = 1$$

Probability density to find particle between radius r and $r+dr$ $\rho(r) = r^2 |R_{n_r}(r)|^2 dr$



Probability depends on volume of shell $\sim r^2 dr$

Reduced radial wave function $u_{n_r}(r) \equiv r R_{n_r}(r)$

$$\text{Normalization } \int_0^{\infty} |u_{n_r}(r)|^2 dr = 1$$

Representation of \hat{p}_r in position

$$\hat{p} \equiv -i\hbar \vec{\nabla} \quad \hat{x} \equiv \vec{x} = r \vec{e}_r$$

$$\hat{p}_r \equiv \frac{1}{2} \left(\frac{\vec{x}}{r} \cdot (-i\hbar \vec{\nabla}) + (-i\hbar \vec{\nabla}) \cdot \left(\frac{\vec{x}}{r} \right) \right)$$

$$\langle \vec{x} | \hat{p}_r | \psi \rangle = -\frac{i\hbar}{2} \left(\frac{\partial \psi}{\partial r} + \vec{\nabla} \cdot (\vec{e}_r \psi) \right)$$

$$= -\frac{i\hbar}{2} \left(\frac{\partial \psi}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \psi) \right) = -\frac{i\hbar}{2} \left(2 \frac{\partial \psi}{\partial r} + \frac{\partial \psi}{\partial r} \right)$$

$$= -i\hbar \left(\frac{\partial}{\partial r} + \frac{1}{r} \right) \psi = -\frac{i\hbar}{r} \frac{\partial}{\partial r} (r \psi)$$

(Next Page)

Thus: In position representation

$$\hat{p}_r \doteq -\frac{i\hbar}{r} \frac{\partial}{\partial r} (r \quad)$$

$$\hat{p}_r^2 = -\frac{\hbar^2}{r} \frac{\partial^2}{\partial r^2} (r \quad)$$

Thus, the differential form of the radial eqn.

$$\frac{-\hbar^2}{2mr} \frac{d^2}{dr^2} (r R_{nr}(r)) + \frac{\hbar^2 l(l+1)}{2mr^2} R_{nr}(r) + V(r) R_{nr}(r) = E_{n,l} R_{nr}(r)$$

Multiply through by r ; use reduced radial funct

$$\Rightarrow \left[-\frac{\hbar^2}{2m} \frac{d^2 u_{nr}}{dr^2} + \frac{\hbar^2 l(l+1)}{2mr^2} + V(r) \right] u_{nr}(r) = E_{n,l} u_{nr}(r)$$

radial equation

Looks like T.I.S.E. in 1D with potential

$$V_{\text{eff}}(r) = V(r) + \frac{\hbar^2 l(l+1)}{2mr^2}$$

However: Only on $\frac{1}{2}$ -line $0 < r < \infty$

\Rightarrow Need boundary condition at $r=0$

Boundary condition at origin

Suppose $V(r)$ is not horribly singular at $r=0$, and does not blow up faster than $\frac{1}{r^2}$

\Rightarrow Near origin the radial equation looks like

$$\frac{\hbar^2}{2m} \left(-\frac{d^2}{dr^2} + \frac{l(l+1)}{2mr^2} \right) u = E u$$

Asymptotically near origin $u(r) \sim C r^s$

$$\Rightarrow -s(s-1) + l(l+1) = 0$$

$$\Rightarrow \text{either } s = l+1 \text{ or } s = -(l+2)$$

\Rightarrow Solution near origin $u \sim \begin{cases} C r^{l+1} \\ \text{or} \\ C \frac{1}{r^{l+2}} \end{cases}$

Physical solution does not blow up. Thus if potential includes origin we must reject the $\frac{1}{r^{l+2}}$ solution

$\Rightarrow u(r) \sim r^{l+1}$ near origin

\Rightarrow Extra boundary condition $u(r=0) = 0$ like wall at ∞

Note: $R = r u(r) \sim r^l$ so for $l \geq 0$ R does not vanish at origin